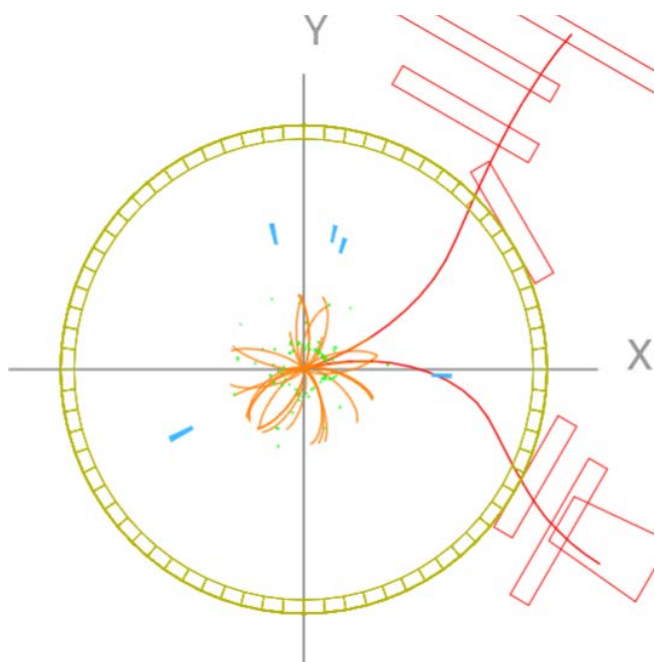
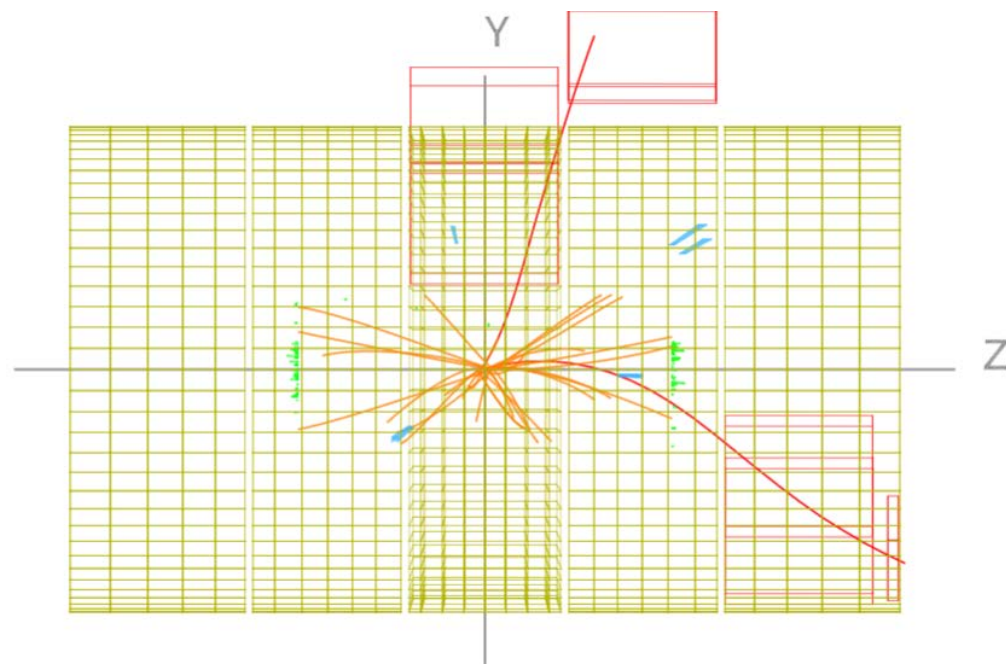


# CMS-W2D2

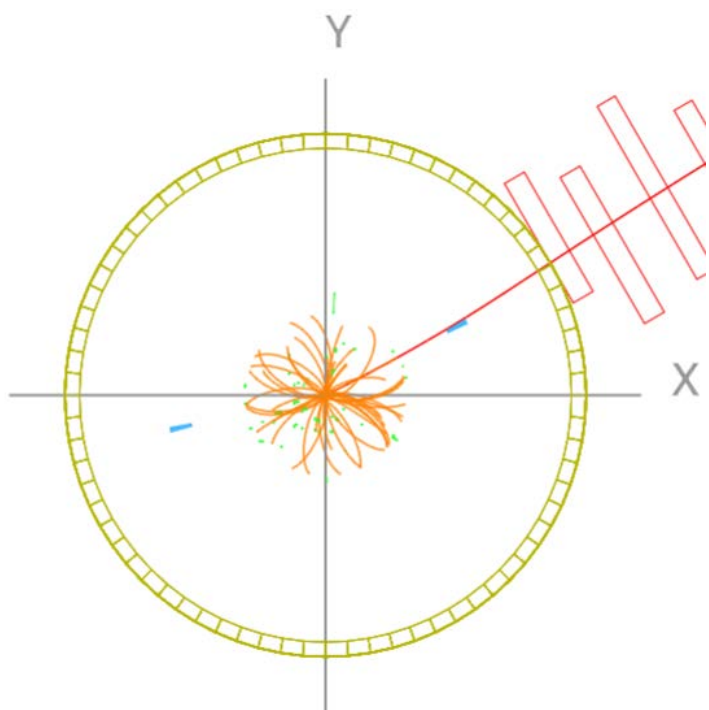
Measurement for  
Masterclass-in-a-box  
Data Set 3



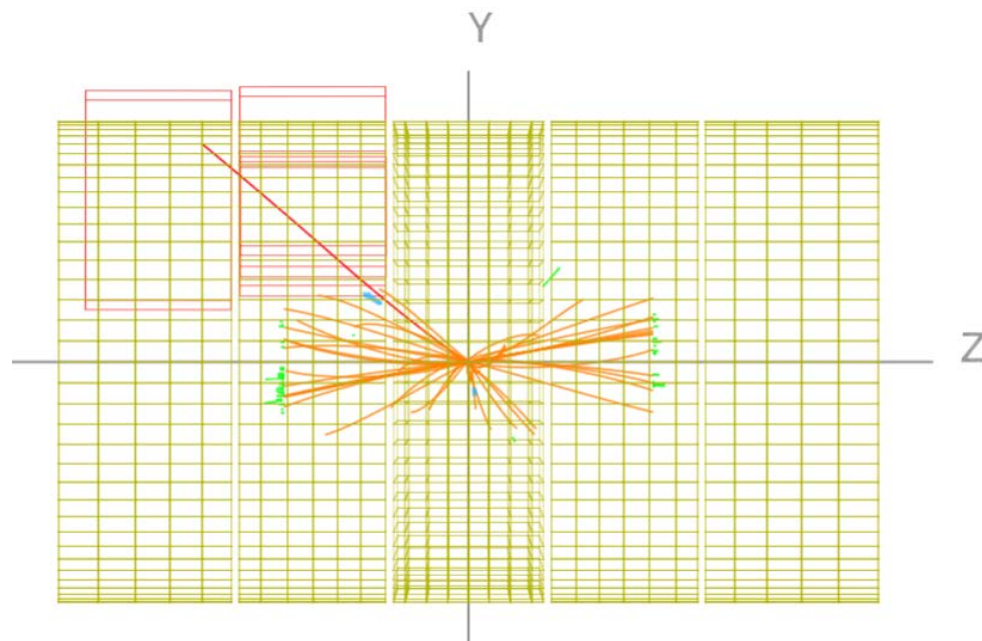
x-y view: measure  $\phi$



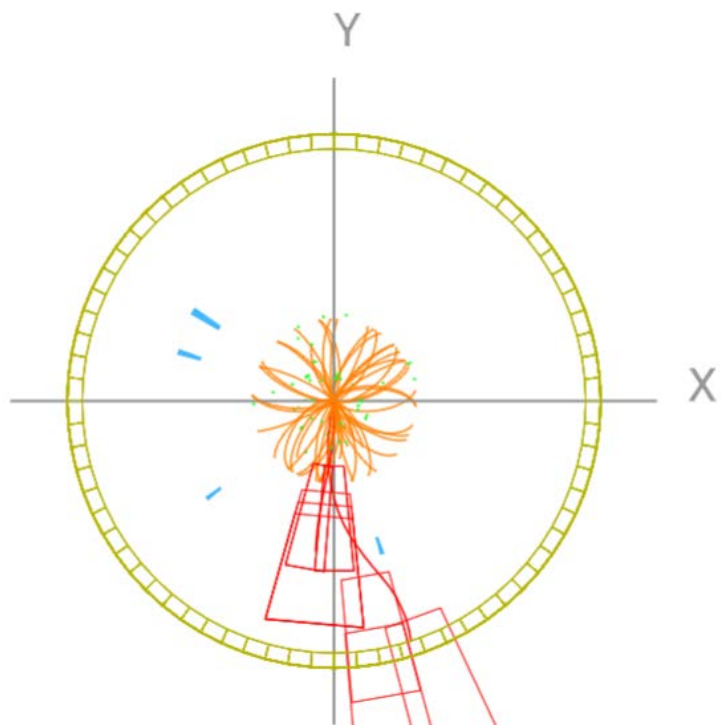
z-y view: measure  $\theta$



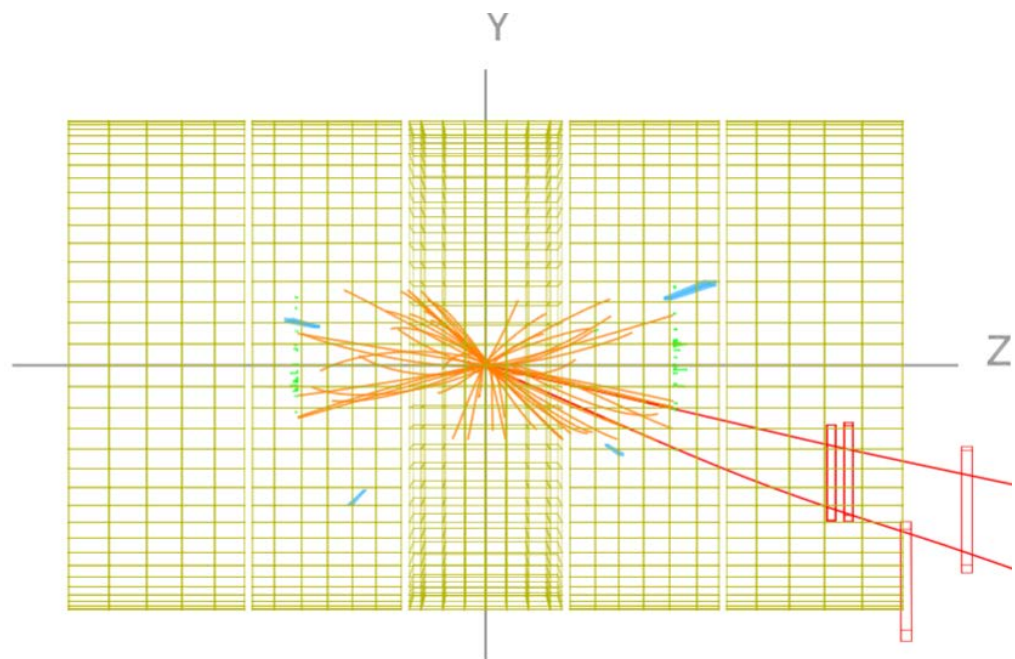
x-y view: measure  $\phi$



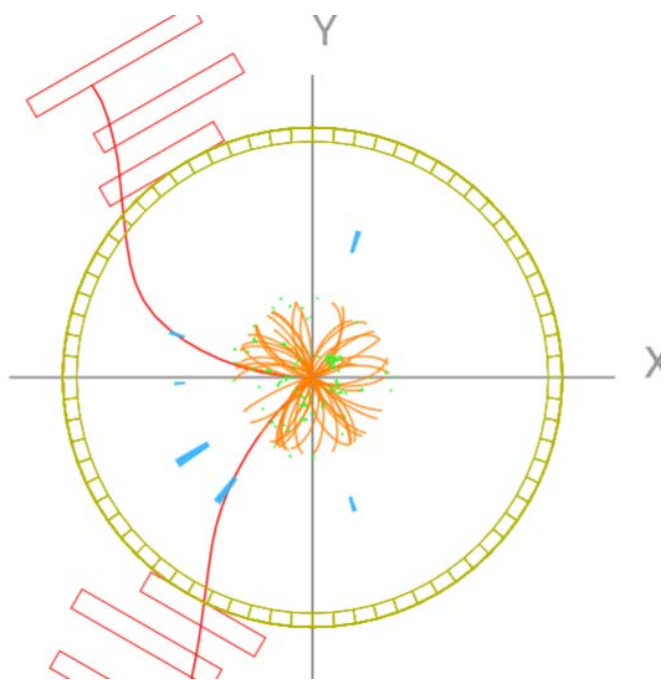
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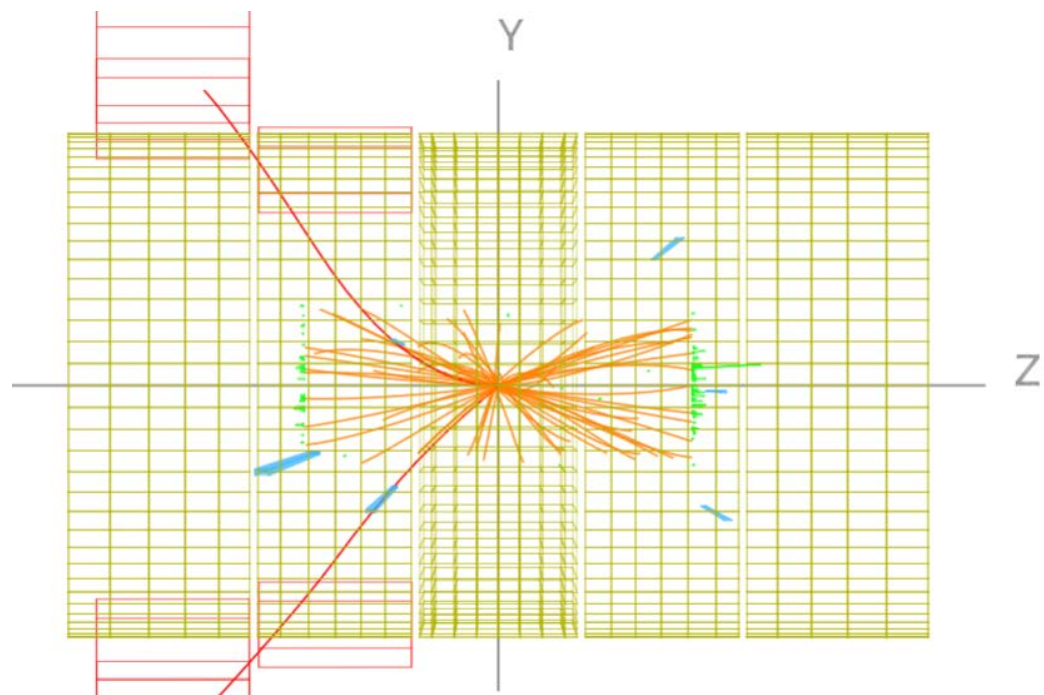
x-y view: measure  $\phi$



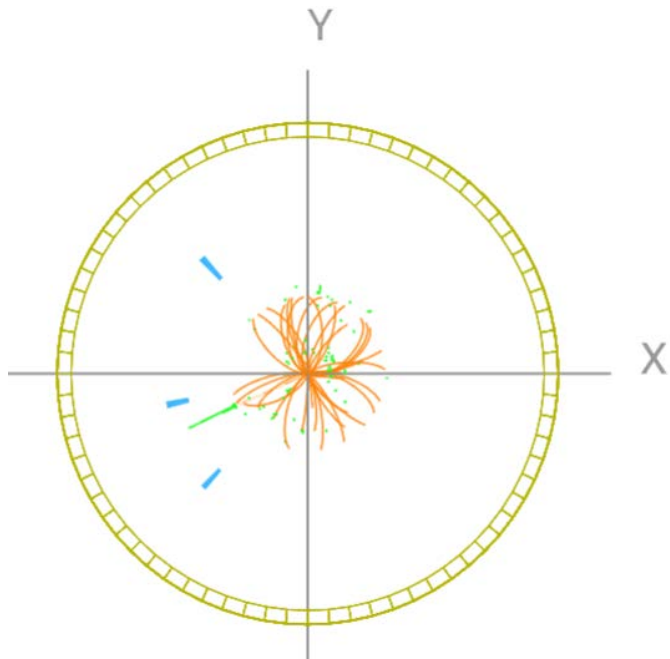
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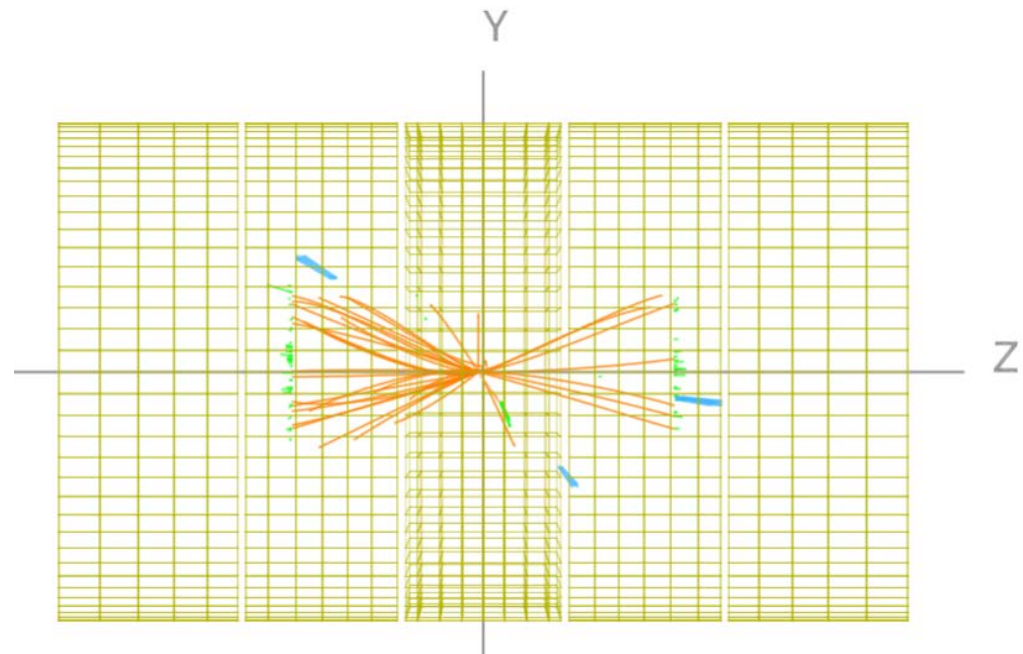
x-y view: measure  $\phi$



z-y view: measure  $\theta$

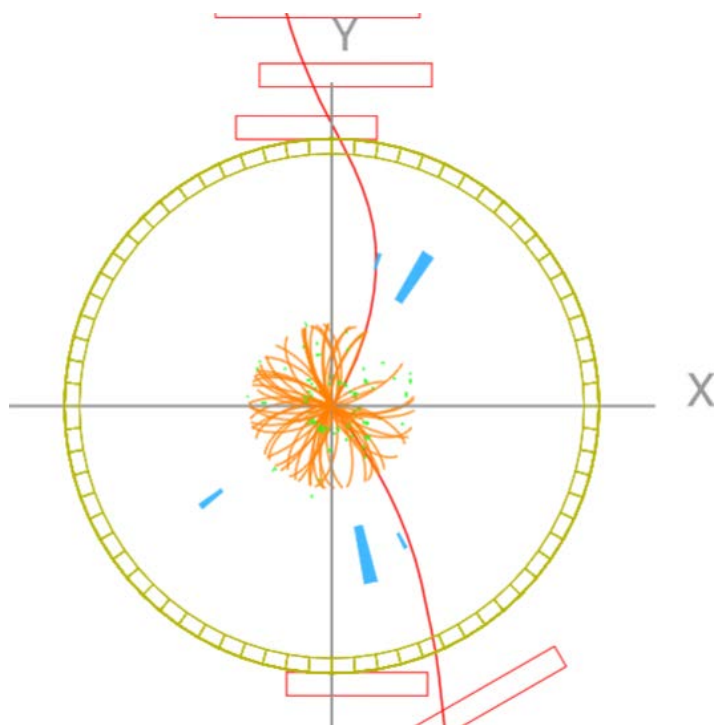


x-y view: measure  $\phi$

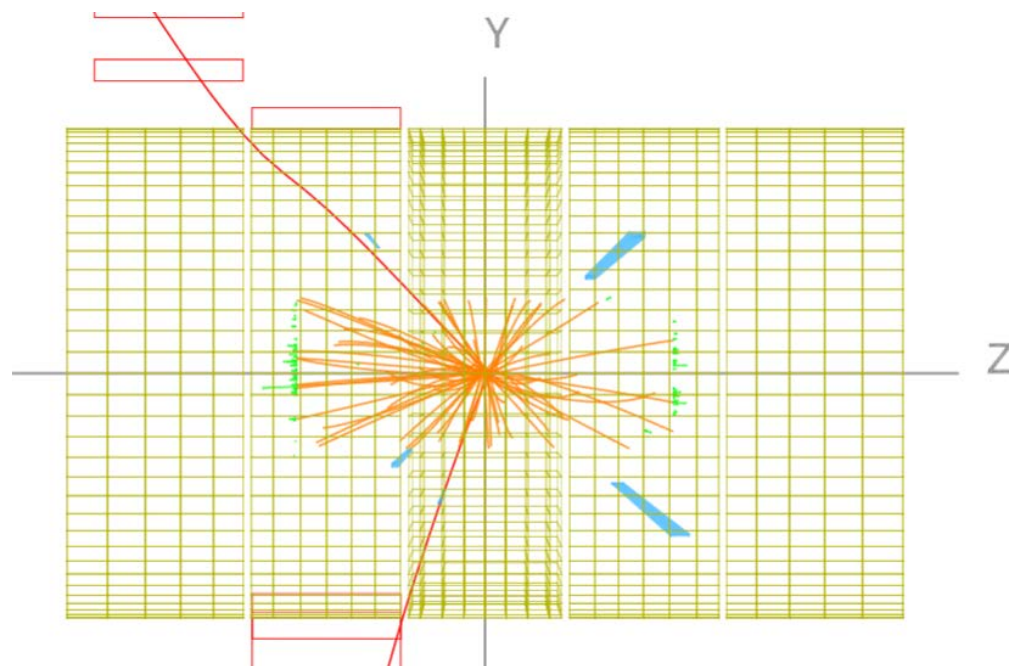


z-y view: measure  $\theta$

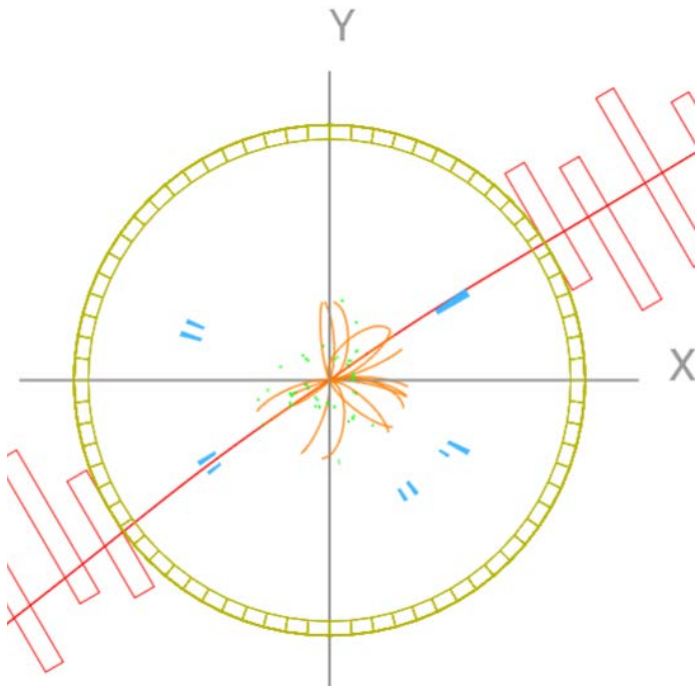




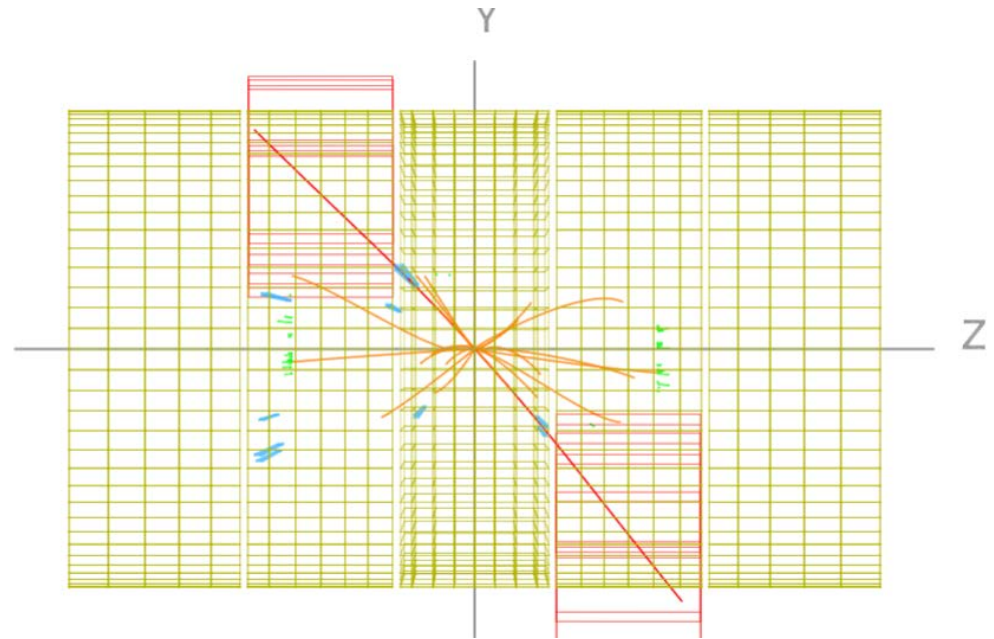
x-y view: measure  $\phi$



z-y view: measure  $\theta$

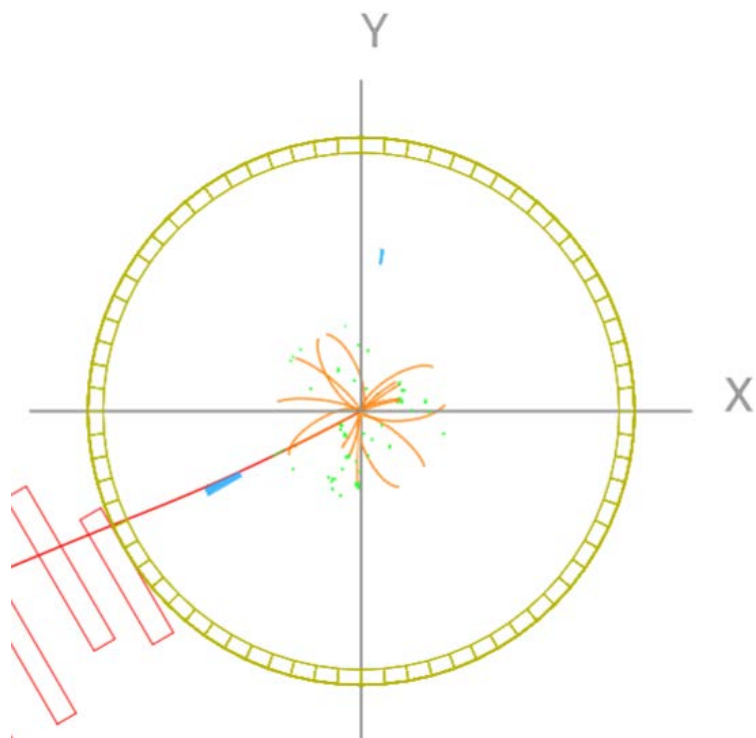
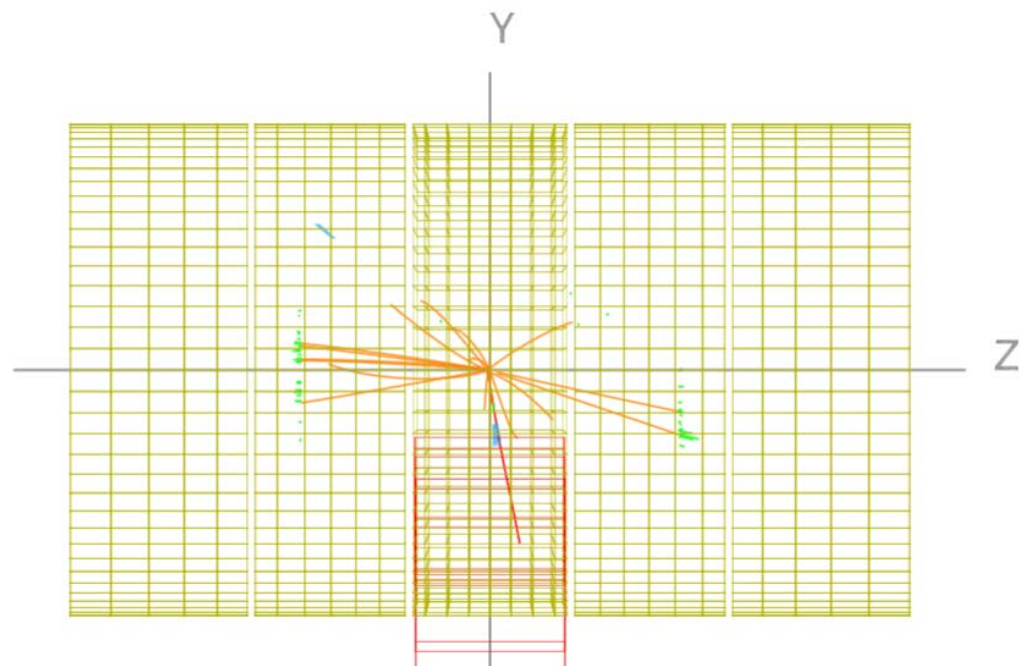


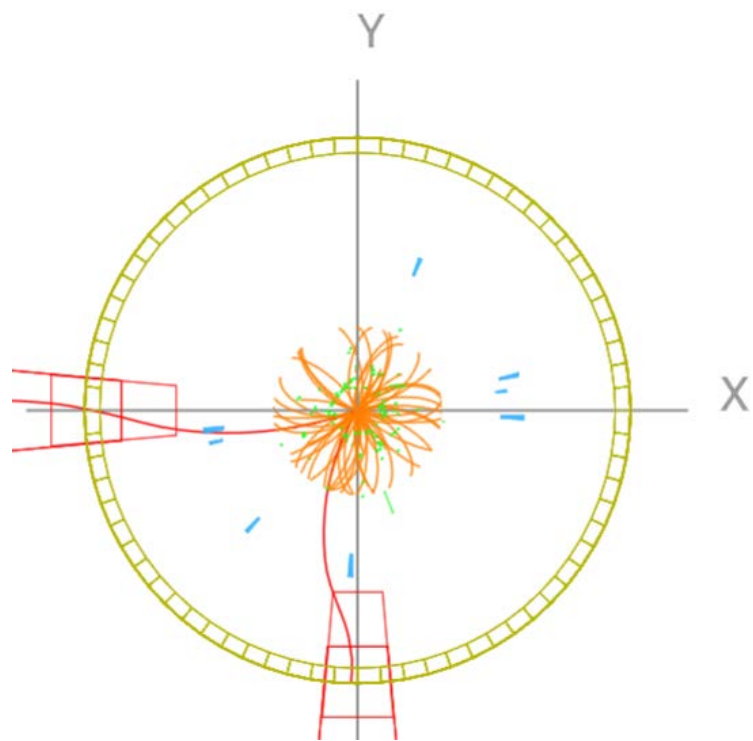
x-y view: measure  $\phi$



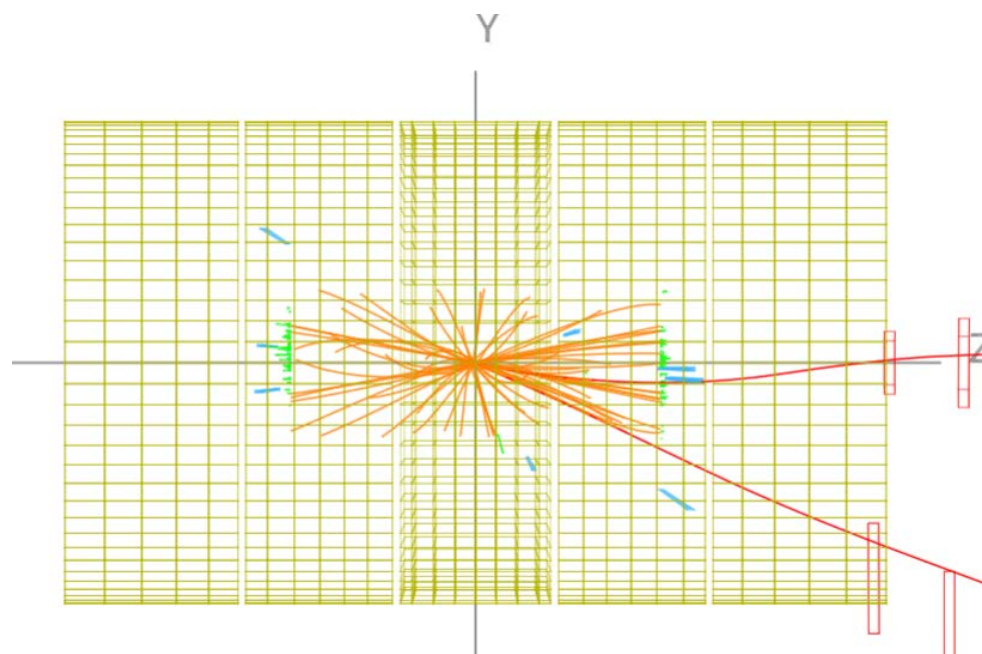
z-y view: measure  $\theta$



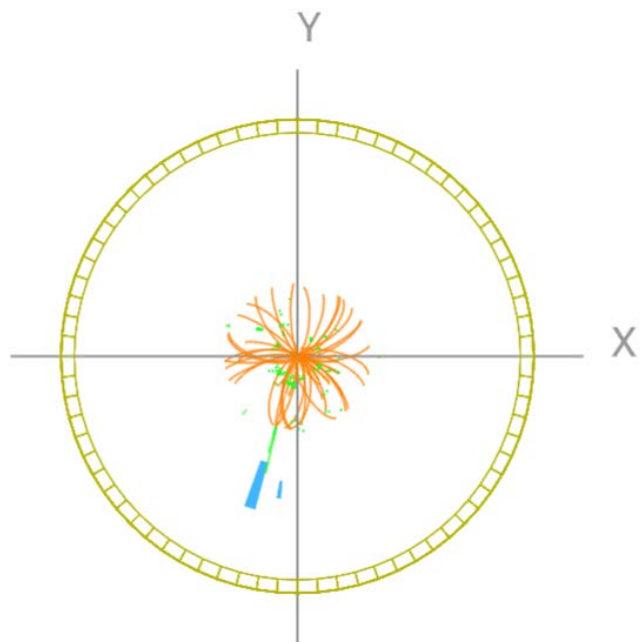
x-y view: measure  $\phi$ z-y view: measure  $\theta$



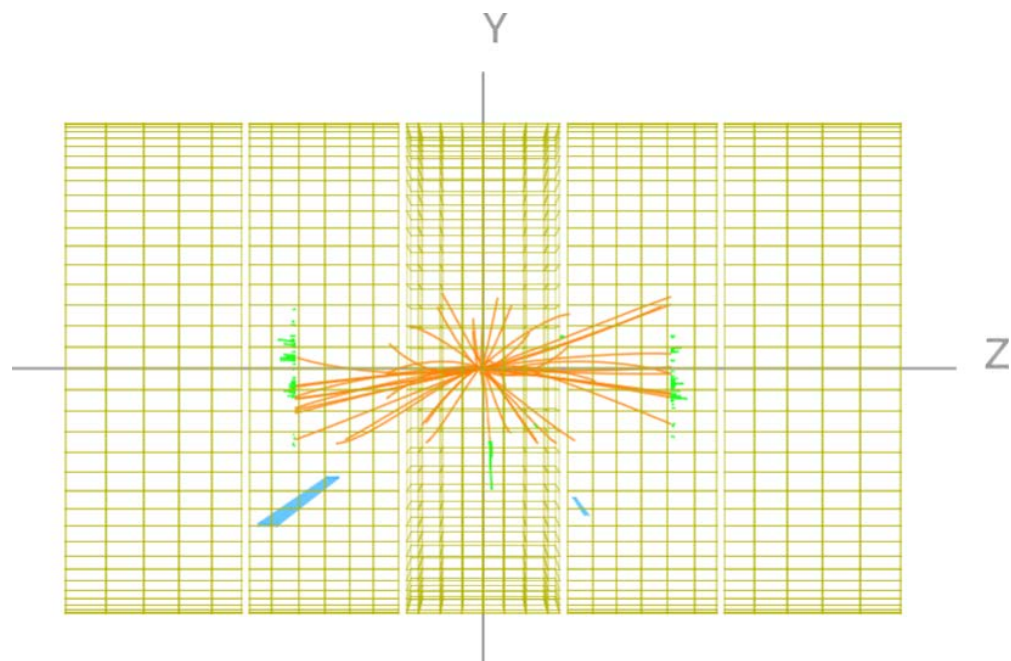
x-y view: measure  $\phi$



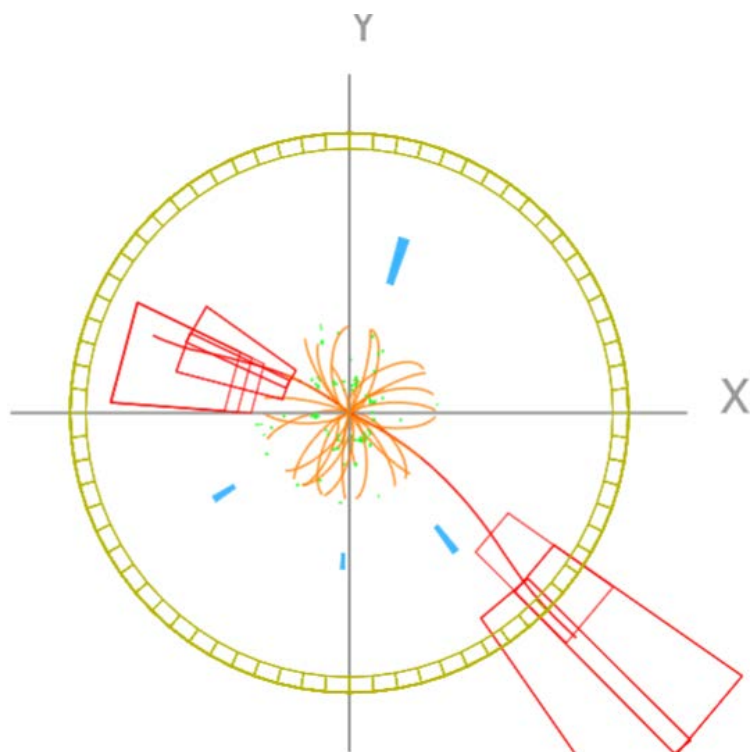
z-y view: measure  $\theta$



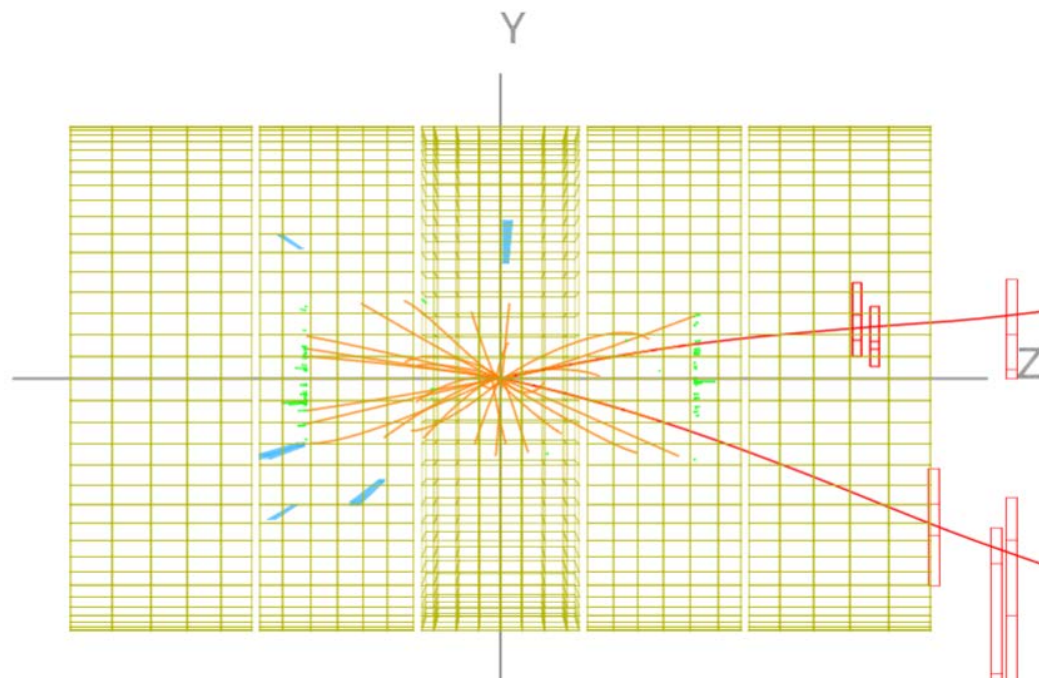
x-y view: measure  $\phi$



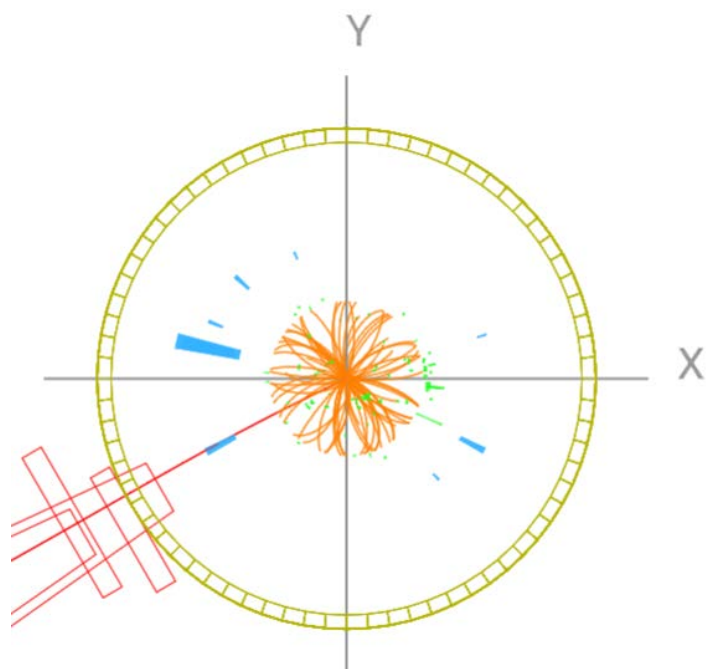
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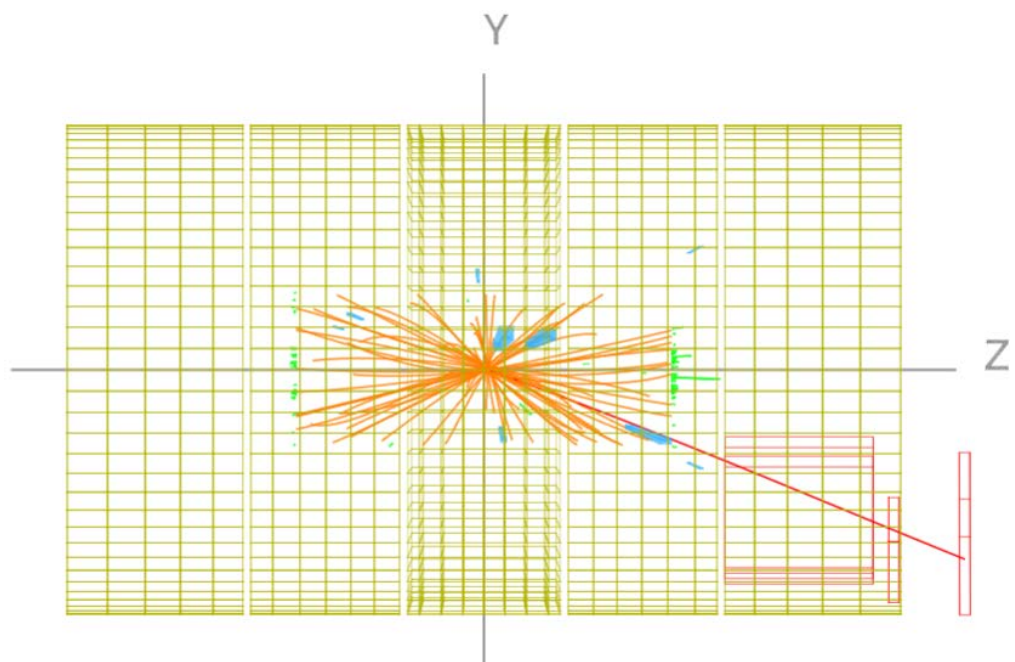
x-y view: measure  $\phi$



z-y view: measure  $\theta$

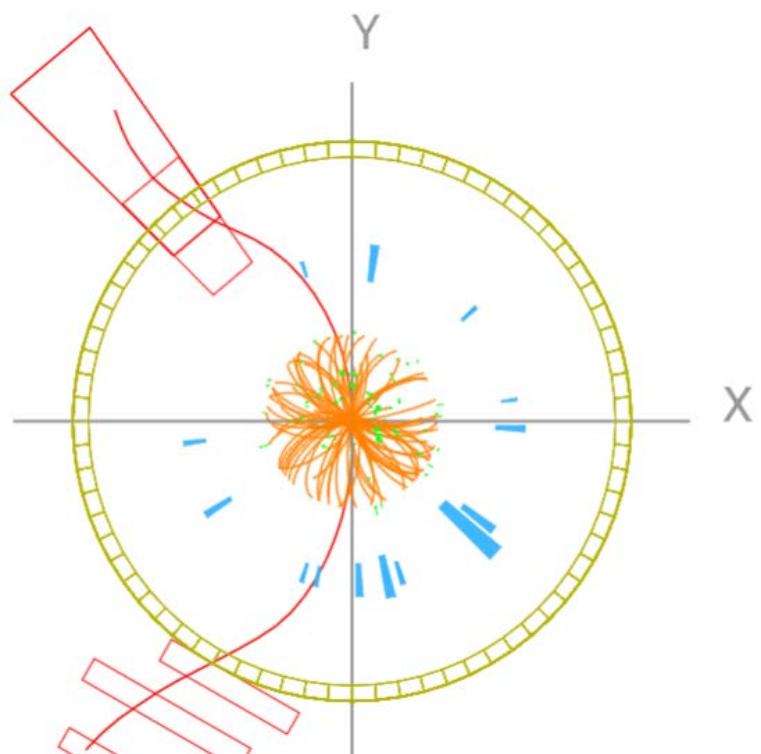


x-y view: measure  $\phi$

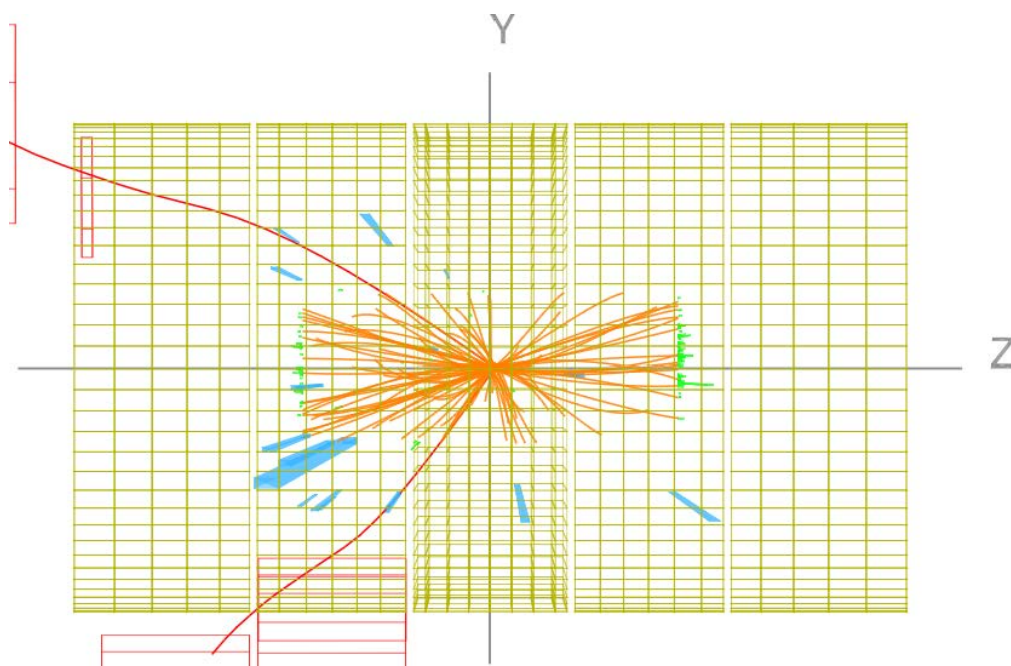


z-y view: measure  $\theta$



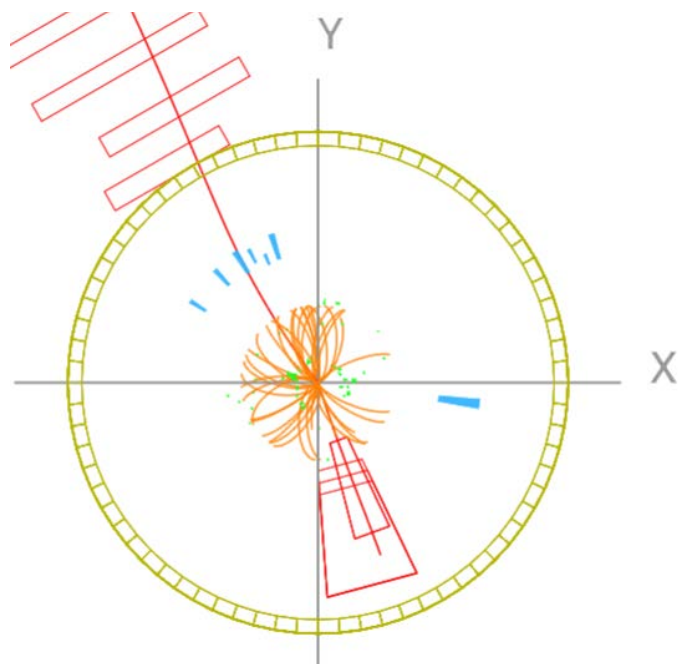


x-y view: measure  $\phi$

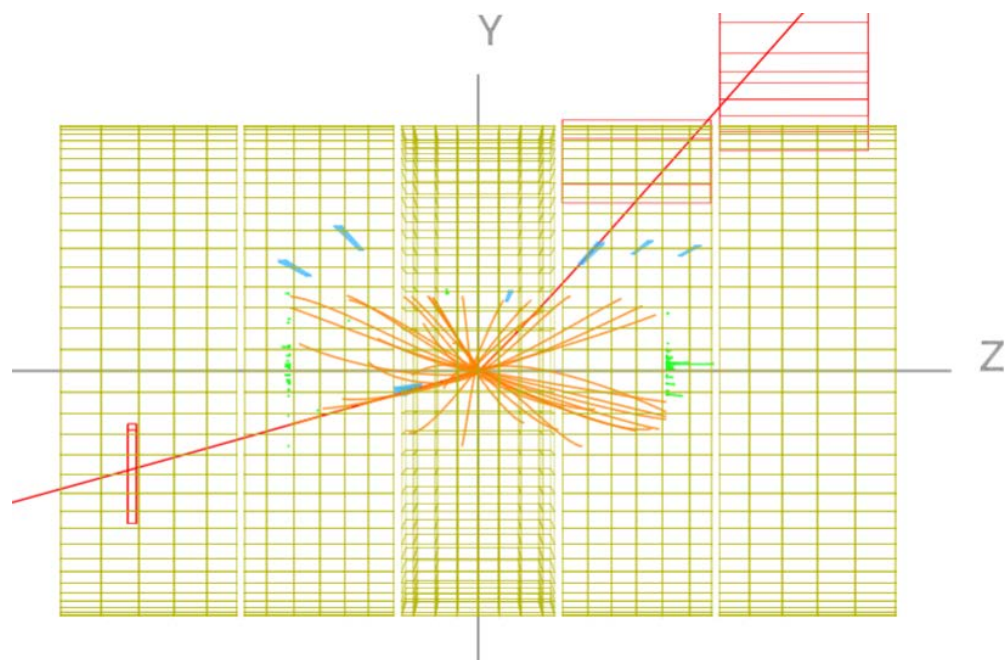


z-y view: measure  $\theta$

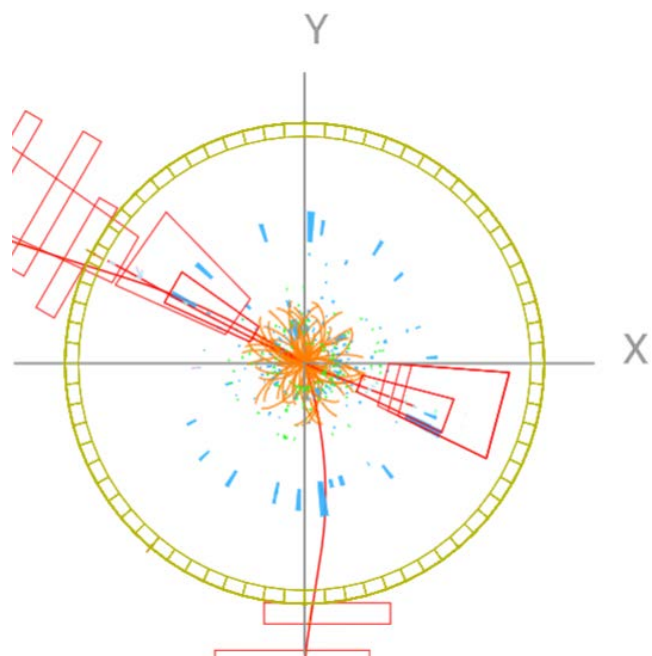




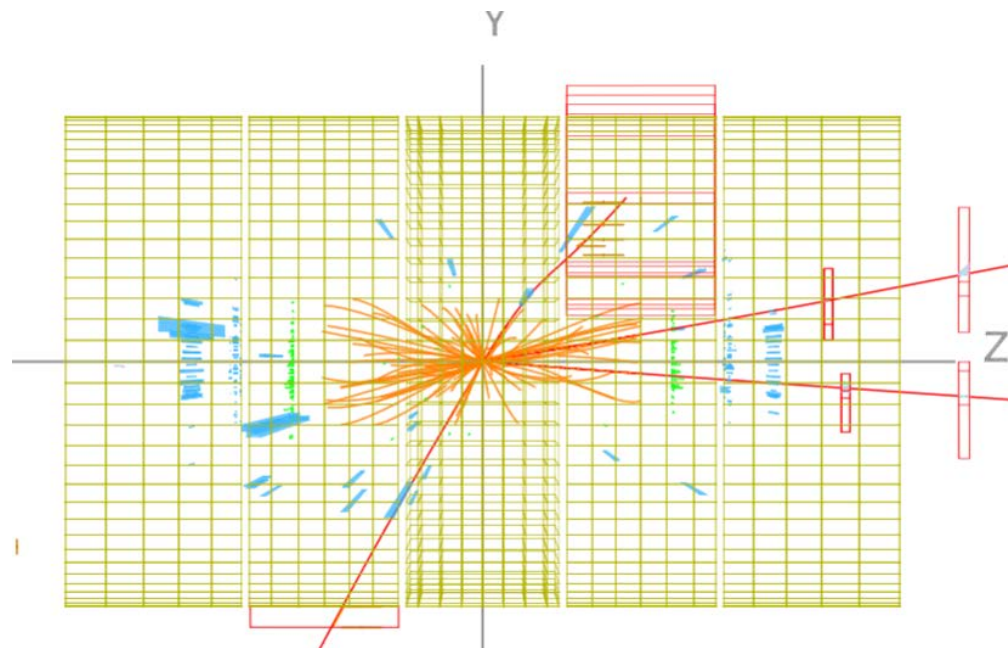
x-y view: measure  $\phi$



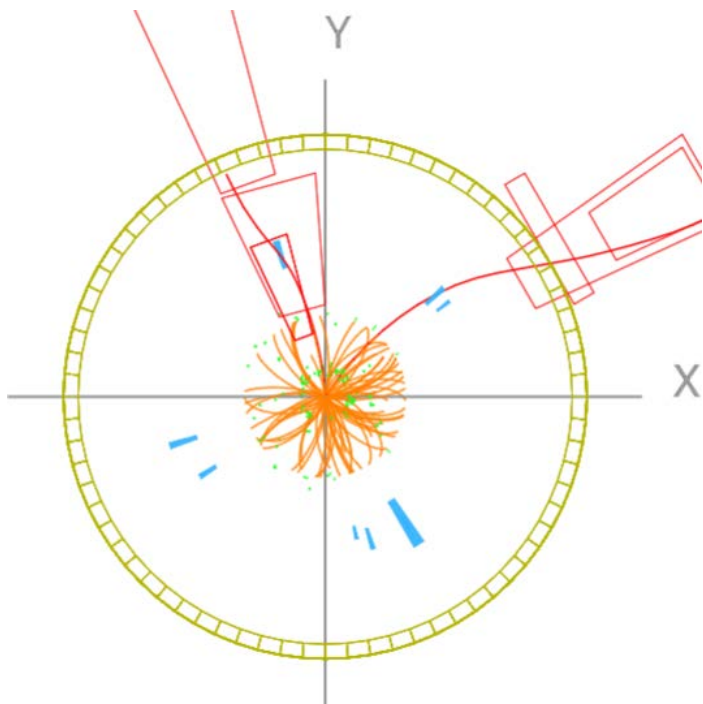
z-y view: measure  $\theta$



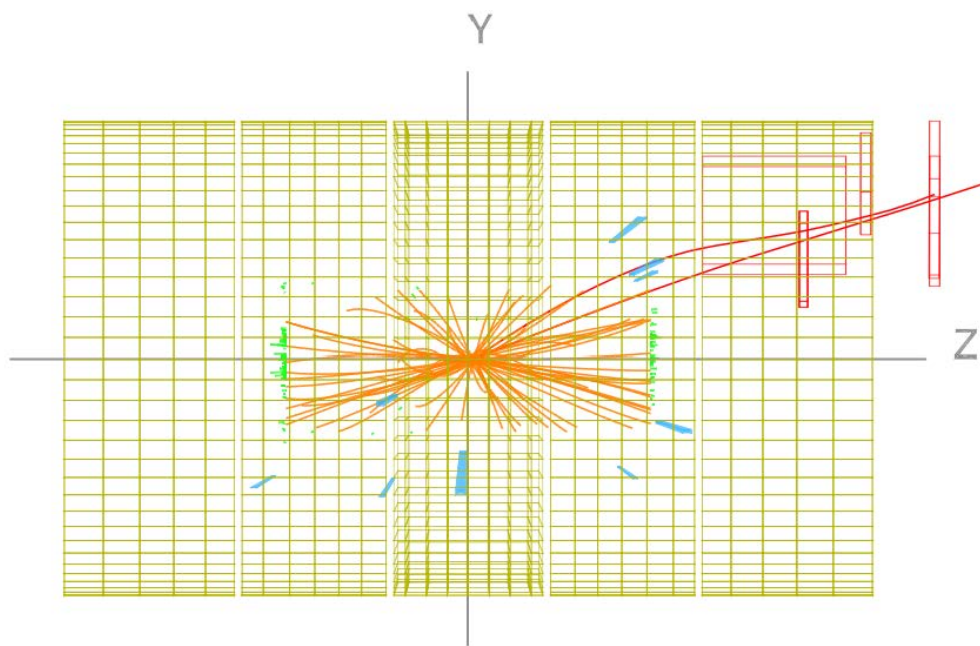
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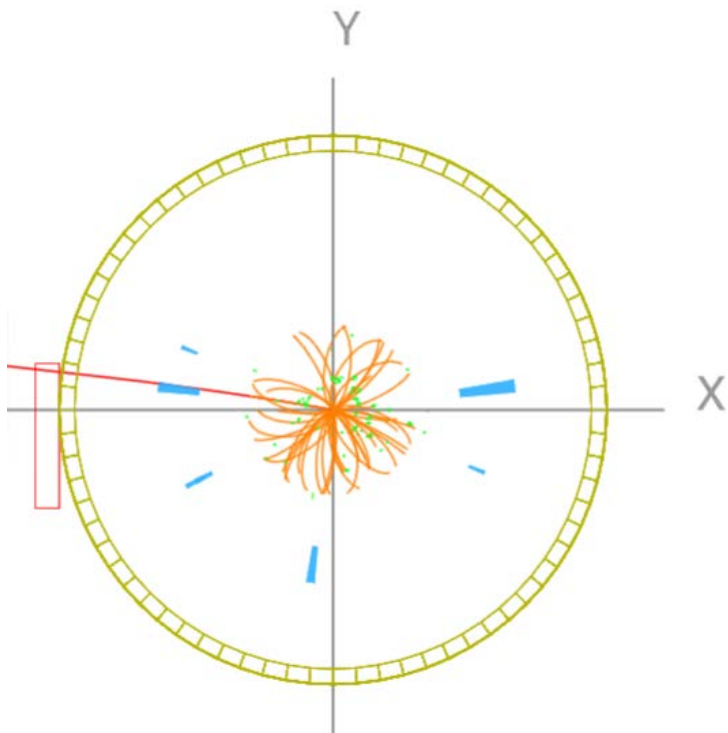
z-y view: measure  $\theta$



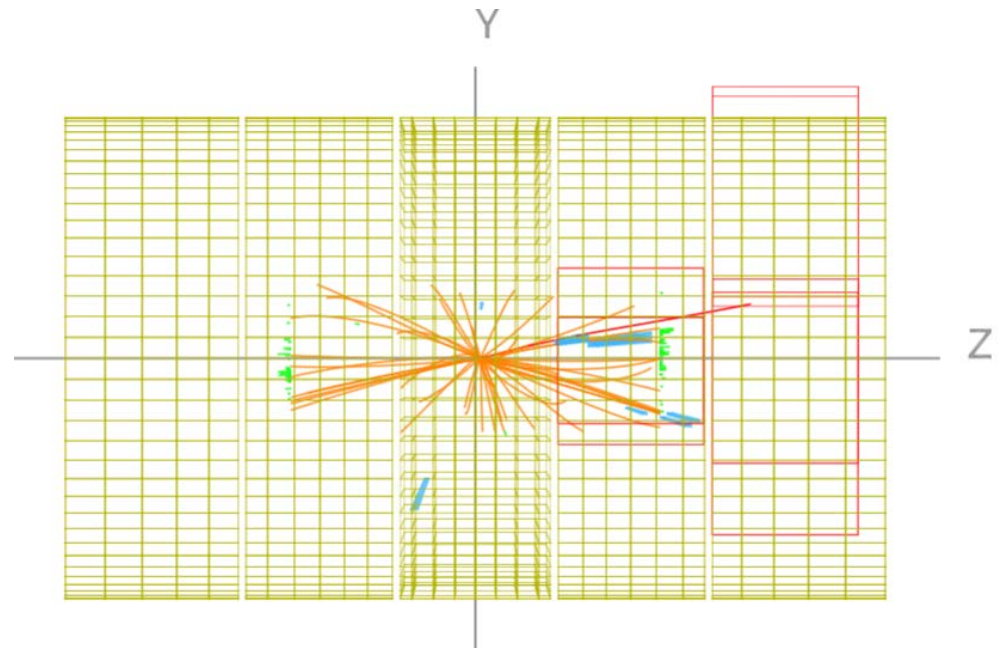
x-y view: measure  $\phi$



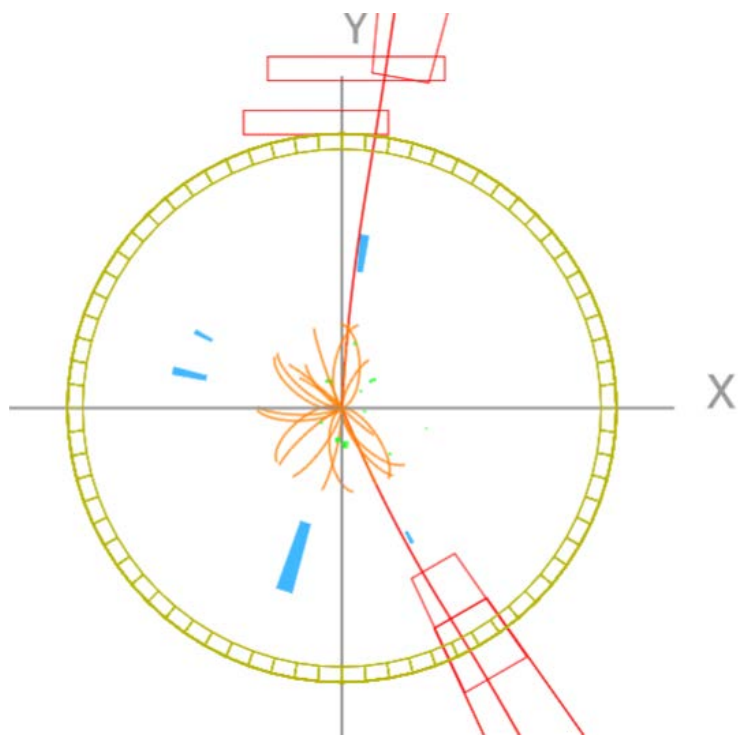
z-y view: measure  $\theta$



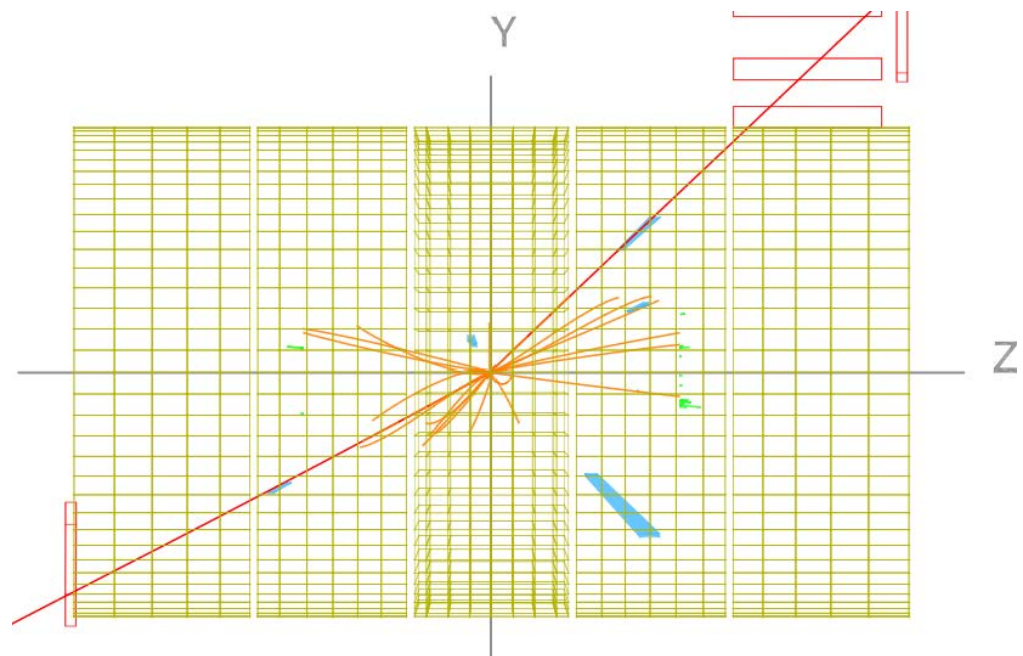
x-y view: measure  $\phi$



z-y view: measure  $\theta$

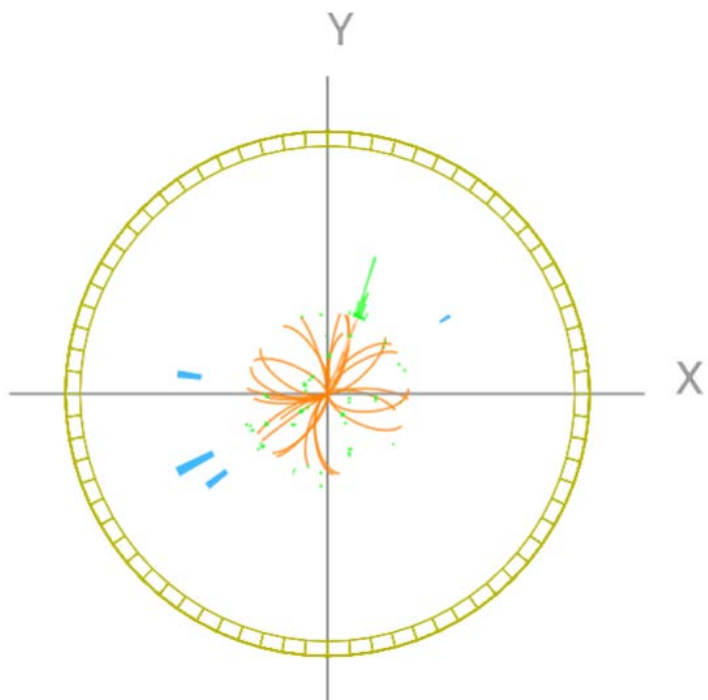


x-y view: measure  $\phi$

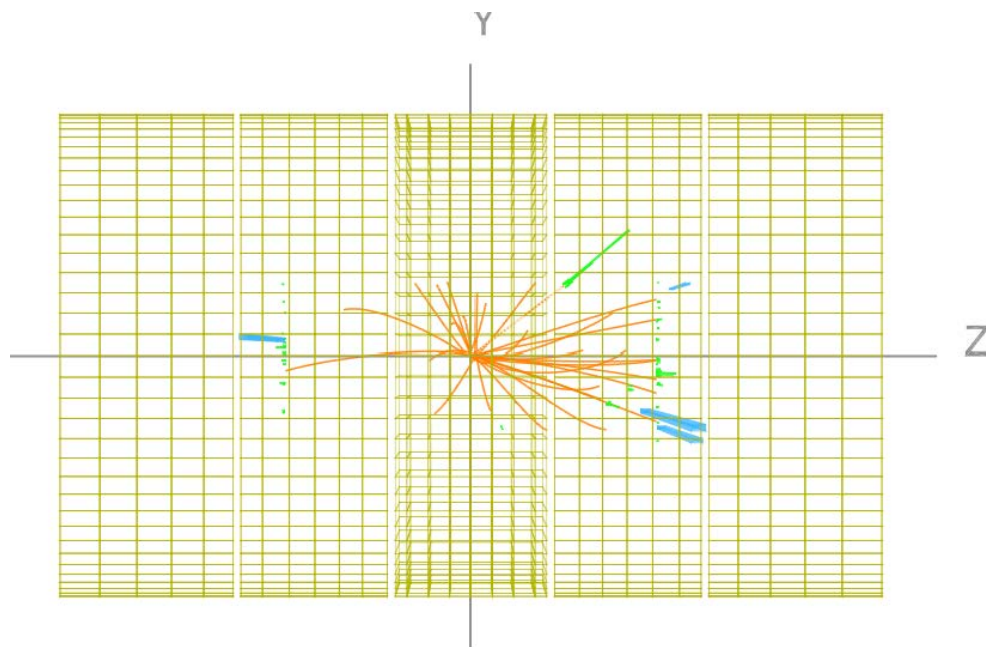


z-y view: measure  $\theta$



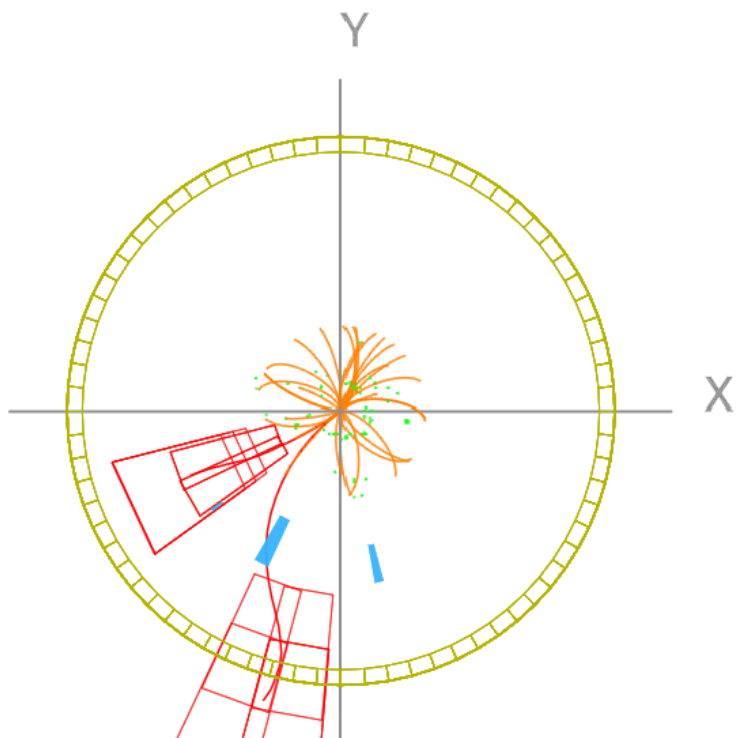


x-y view: measure  $\phi$

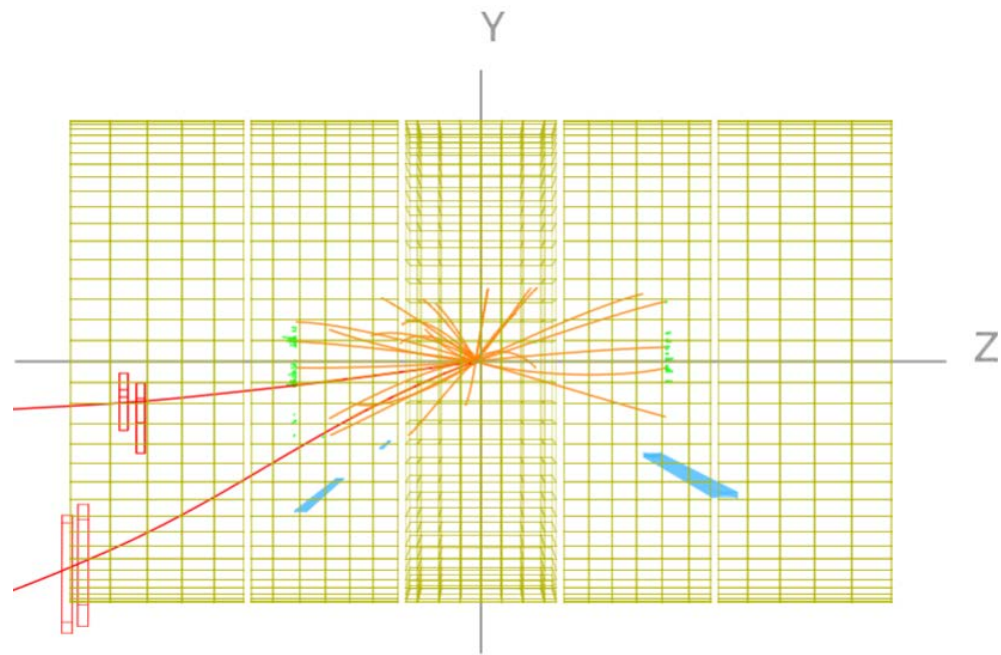


z-y view: measure  $\theta$

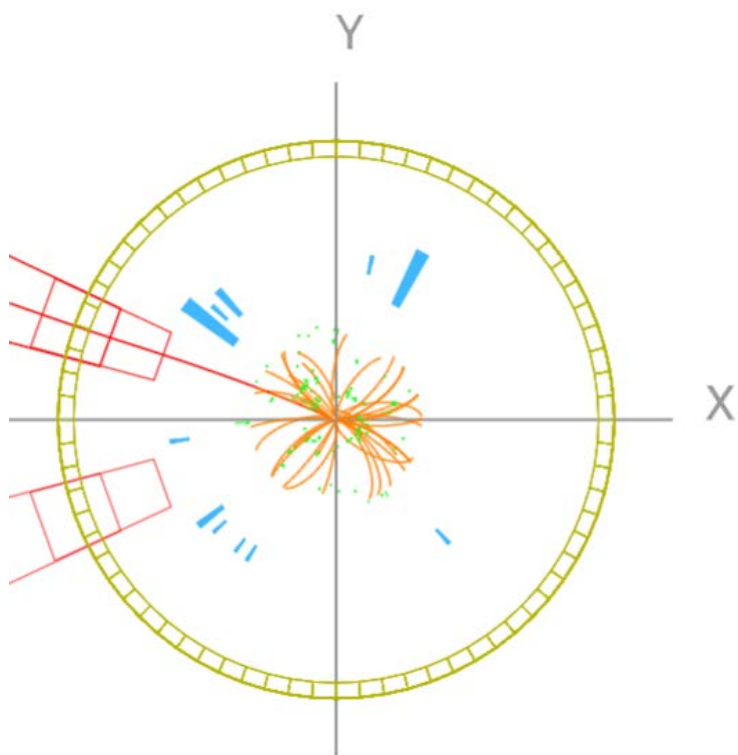




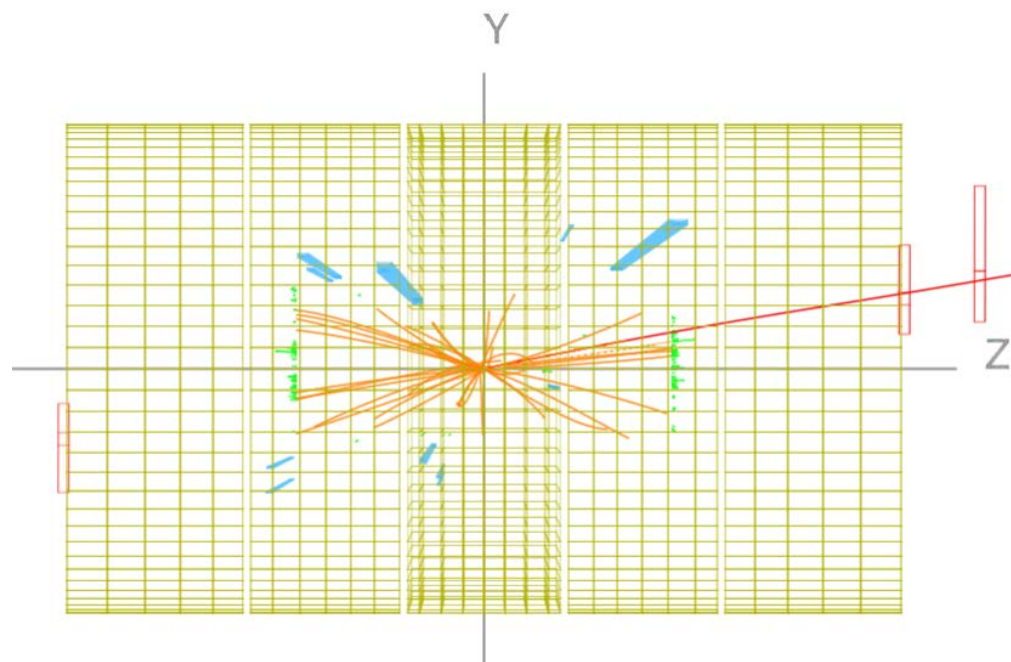
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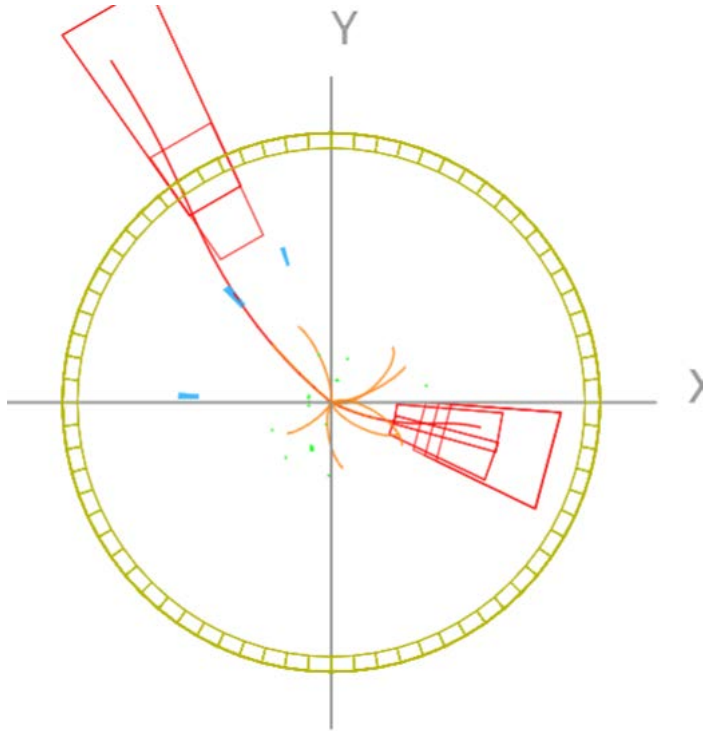
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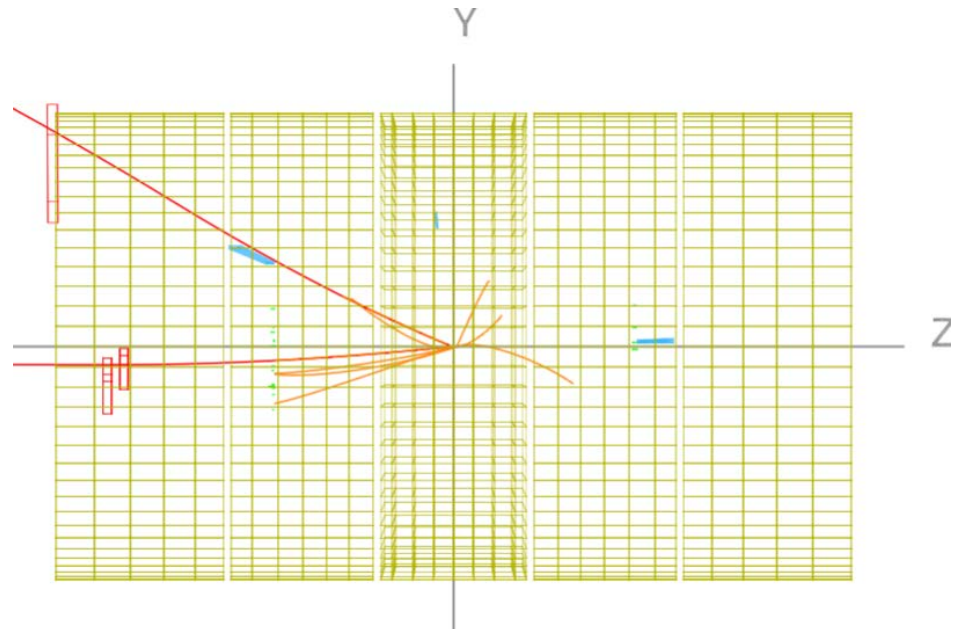
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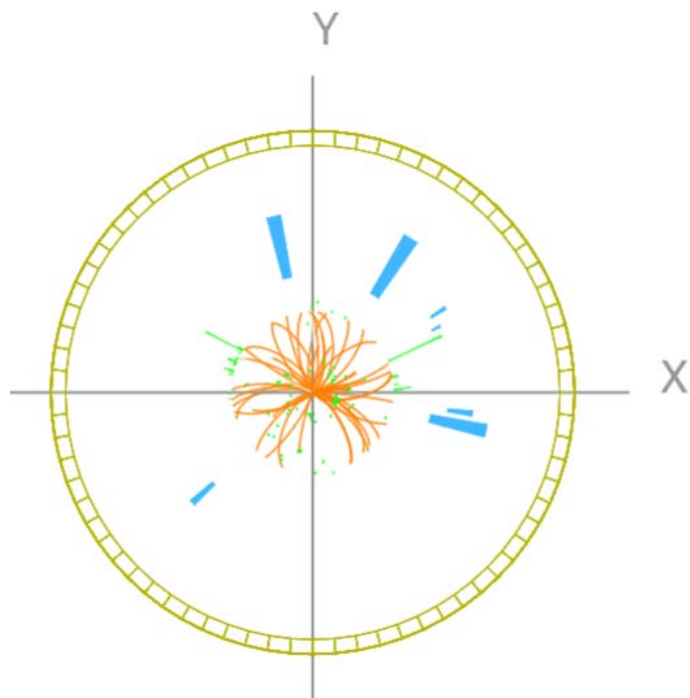
z-y view: measure  $\theta$



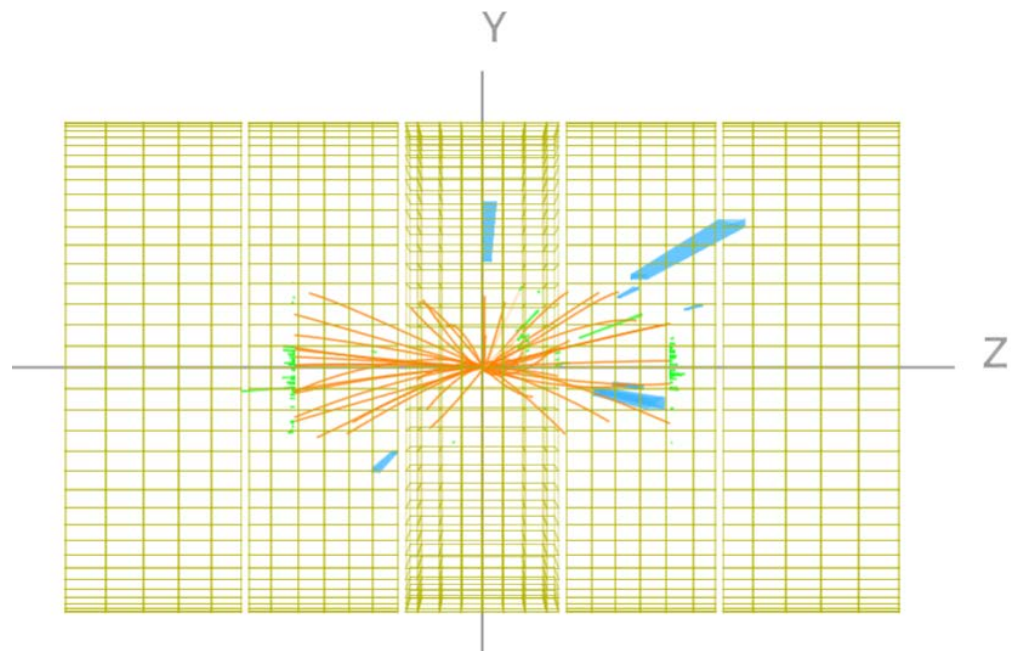
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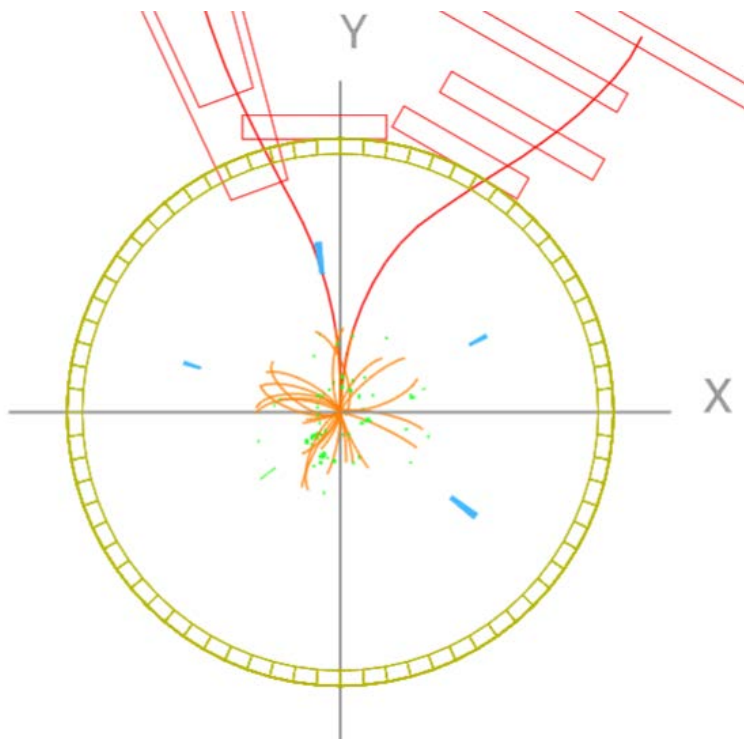
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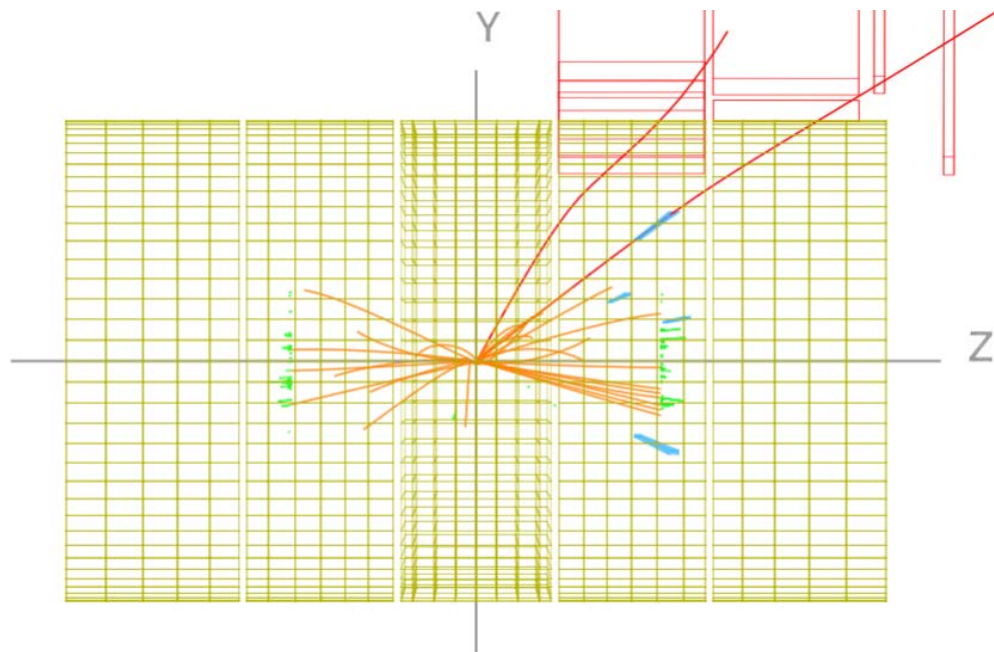
x-y view: measure  $\phi$



z-y view: measure  $\theta$

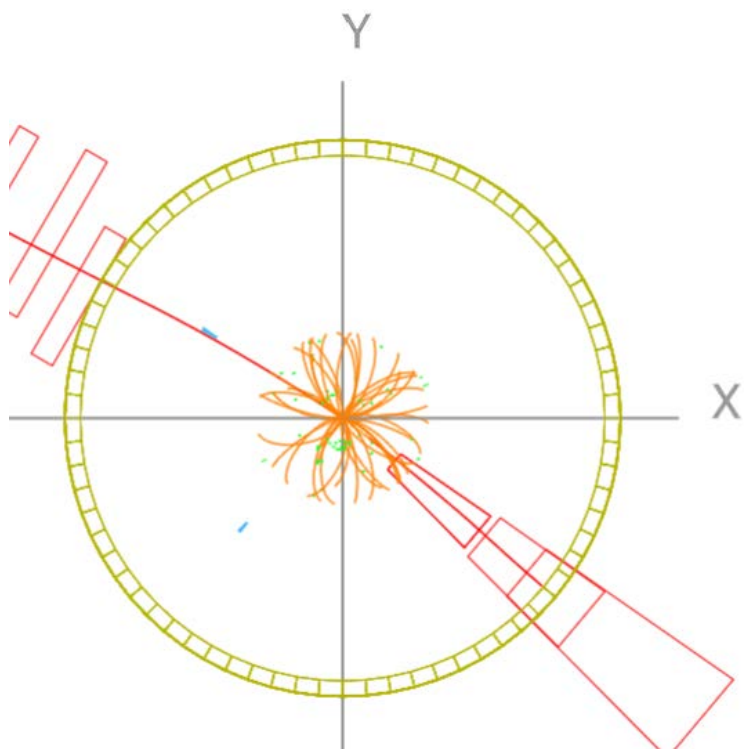


x-y view: measure  $\phi$

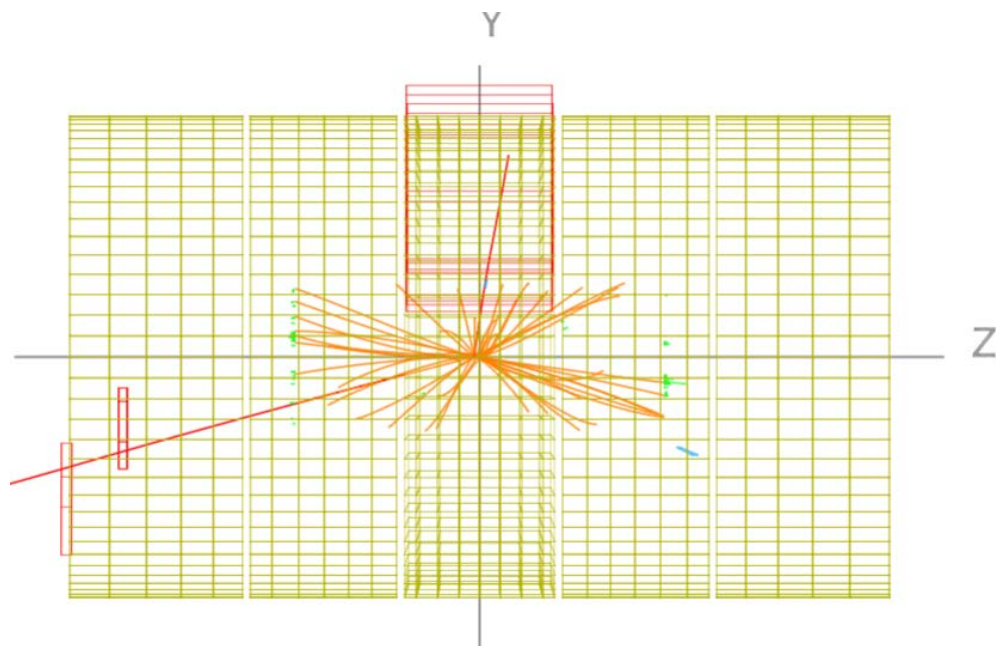


z-y view: measure  $\theta$



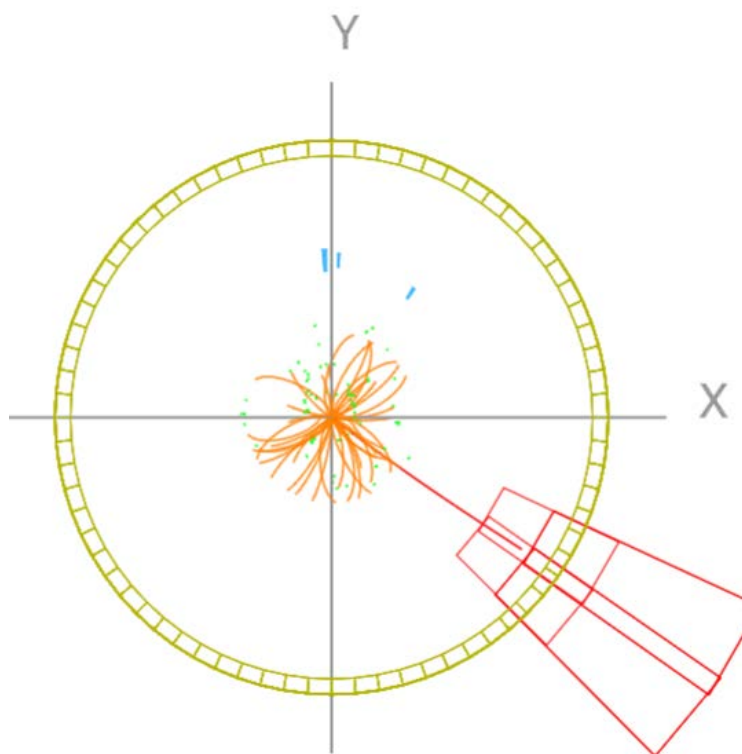


x-y view: measure  $\phi$

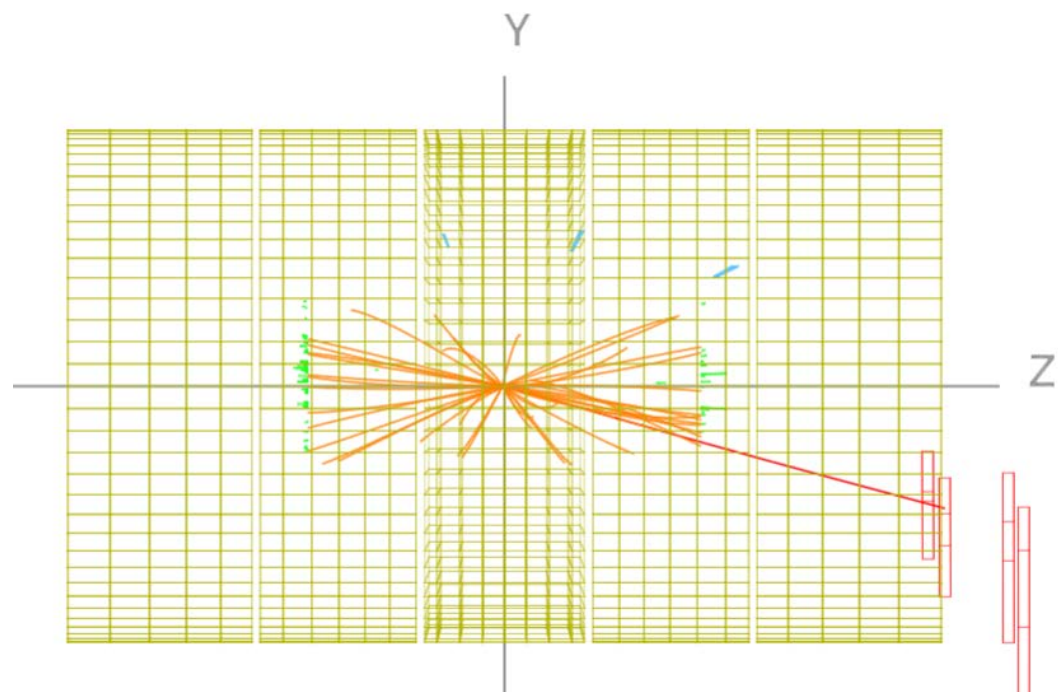


z-y view: measure  $\theta$

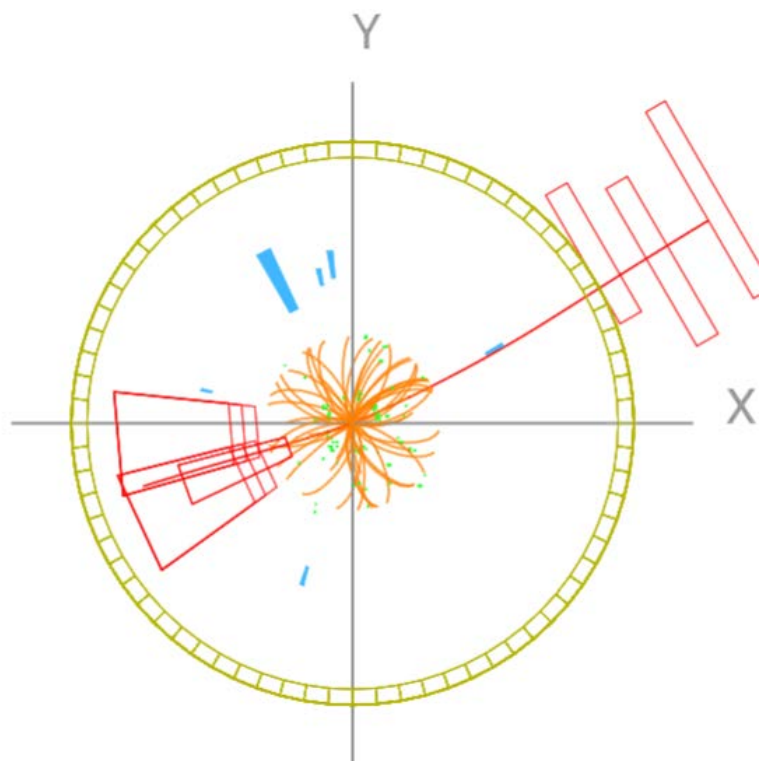




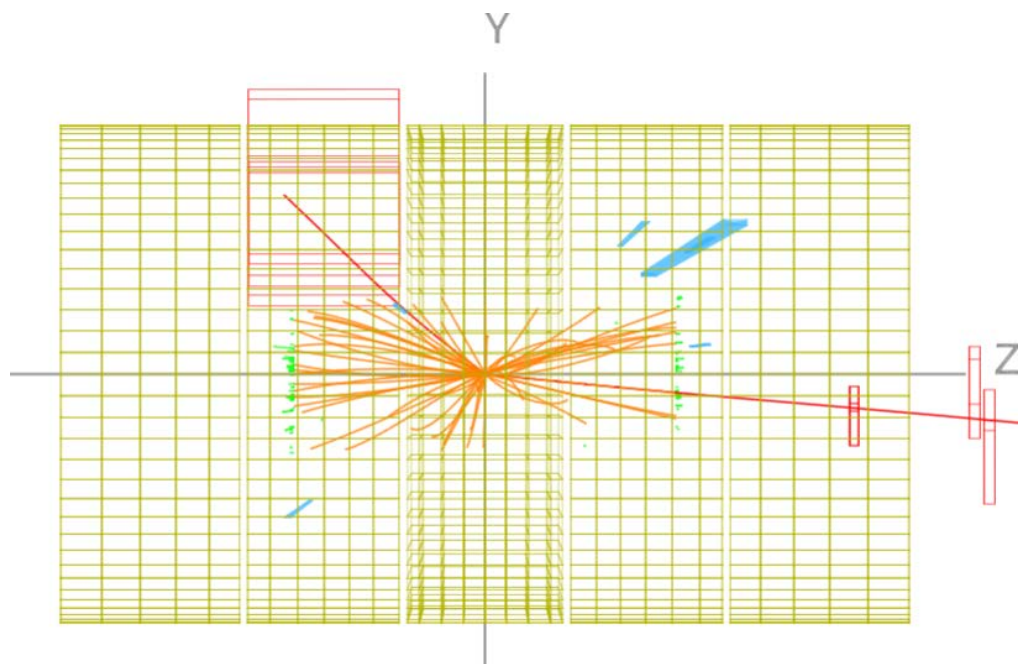
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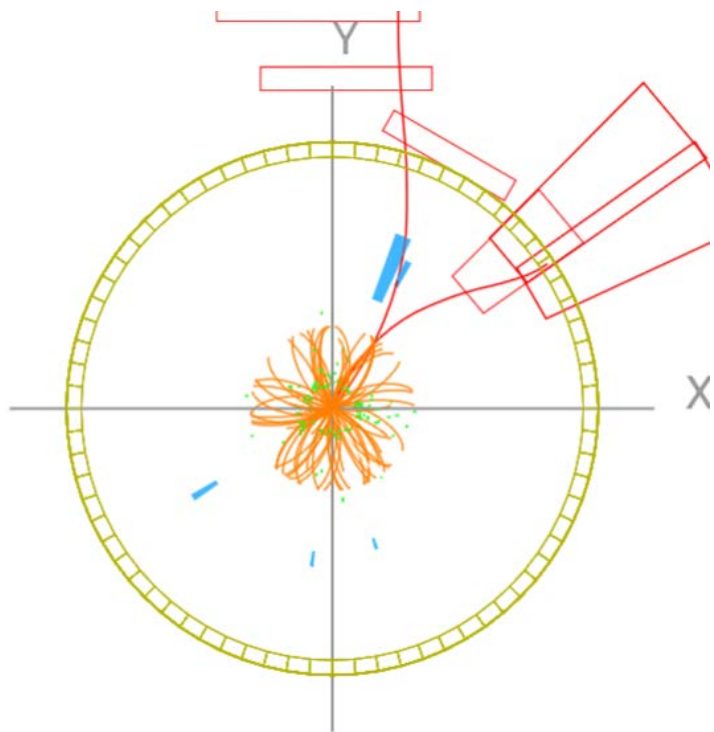
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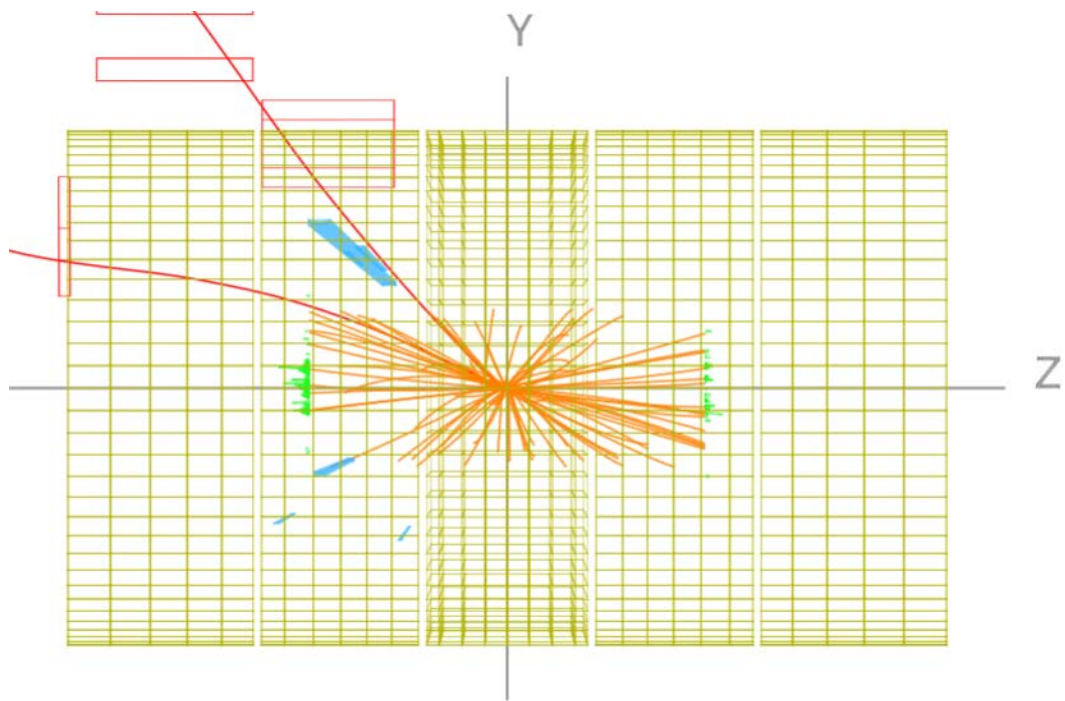
x-y view: measure  $\phi$



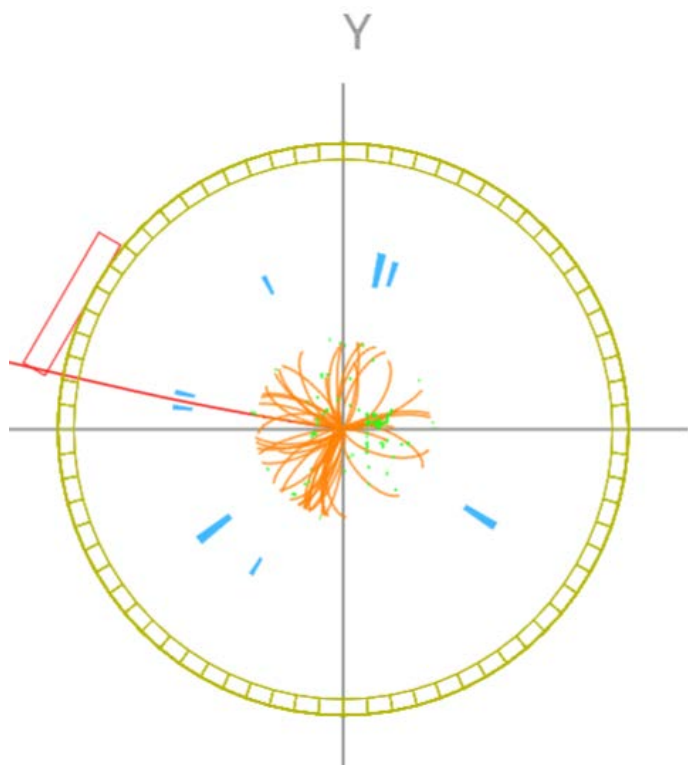
z-y view: measure  $\theta$



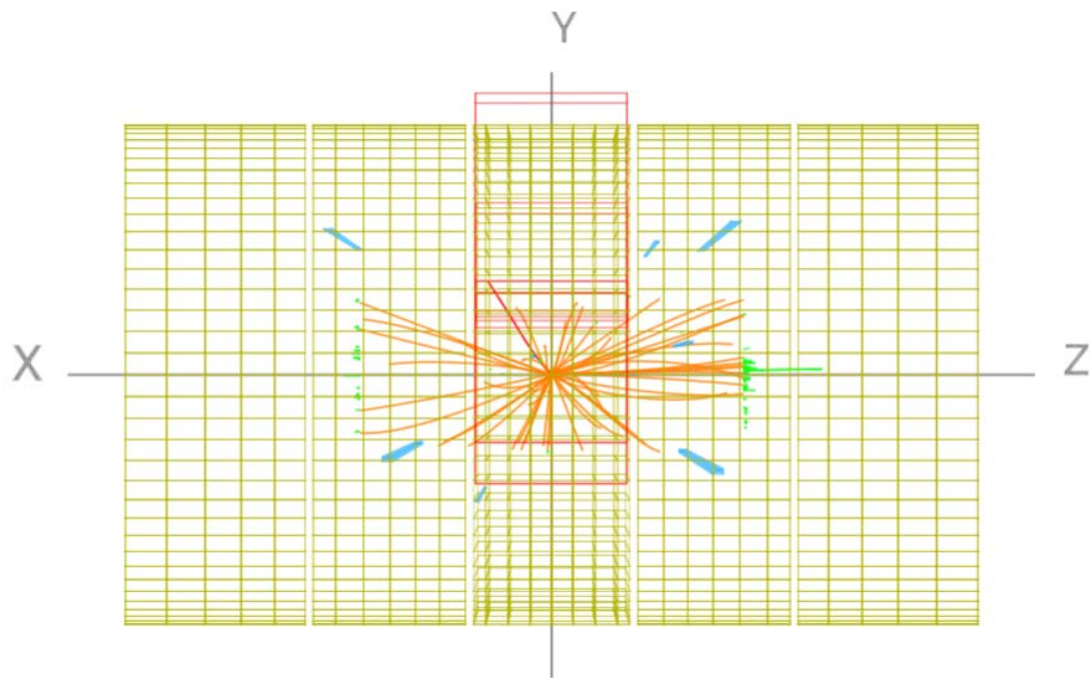
x-y view: measure  $\phi$



z-y view: measure  $\theta$

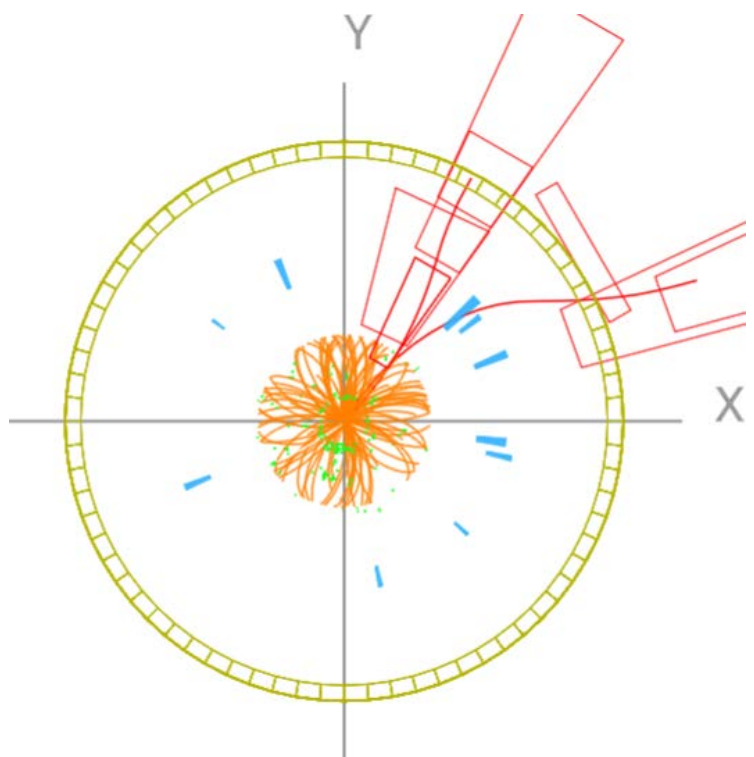


x-y view: measure  $\phi$

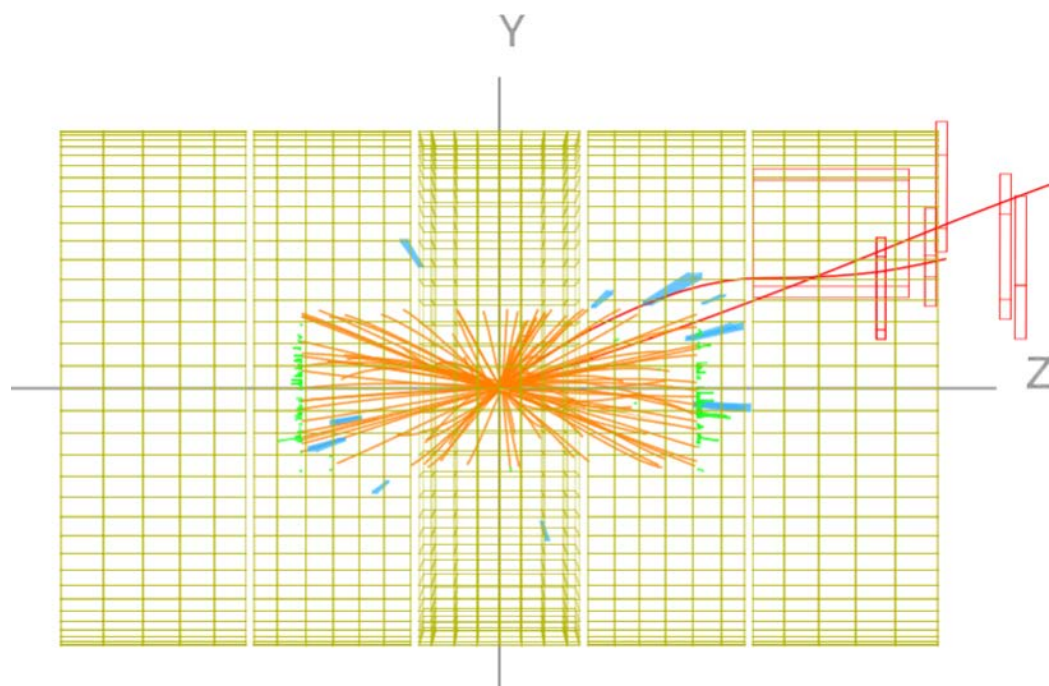


z-y view: measure  $\theta$

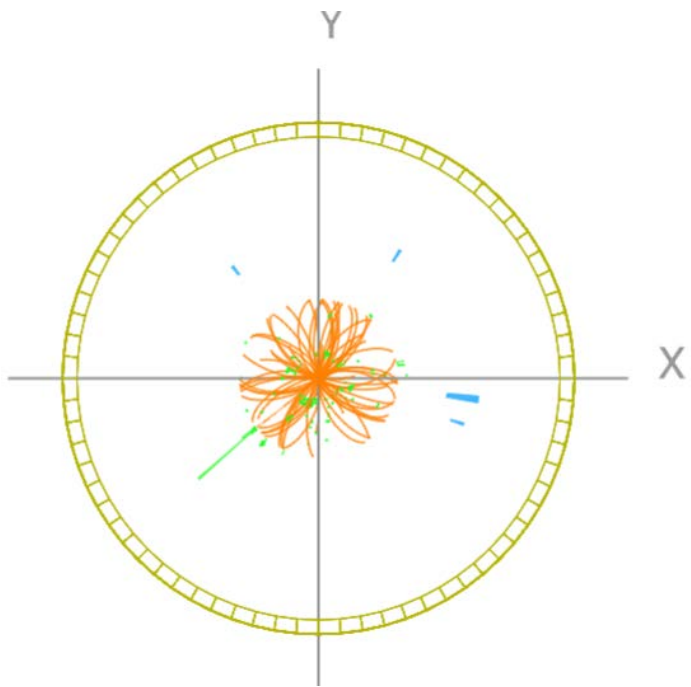




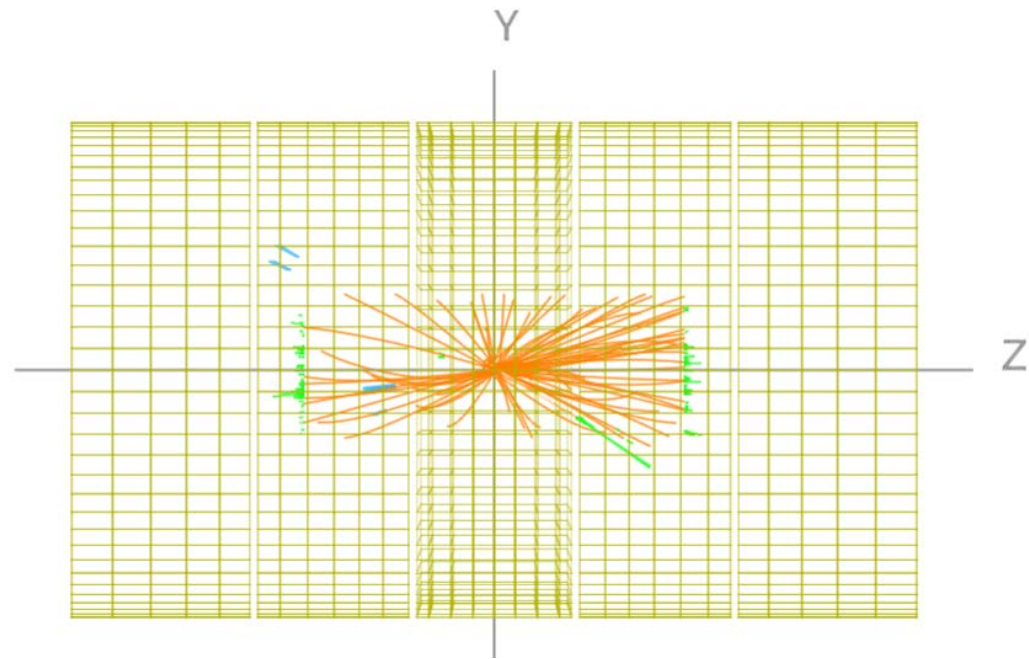
x-y view: measure  $\phi$



z-y view: measure  $\theta$

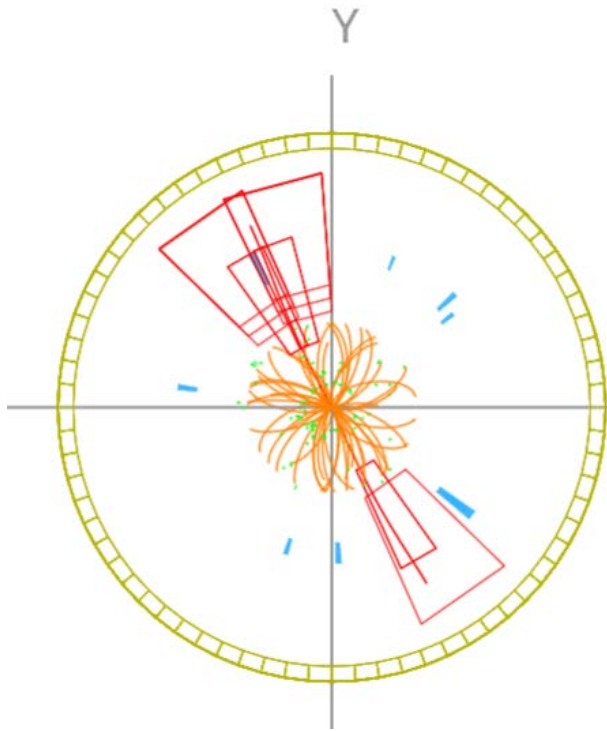


x-y view: measure  $\phi$

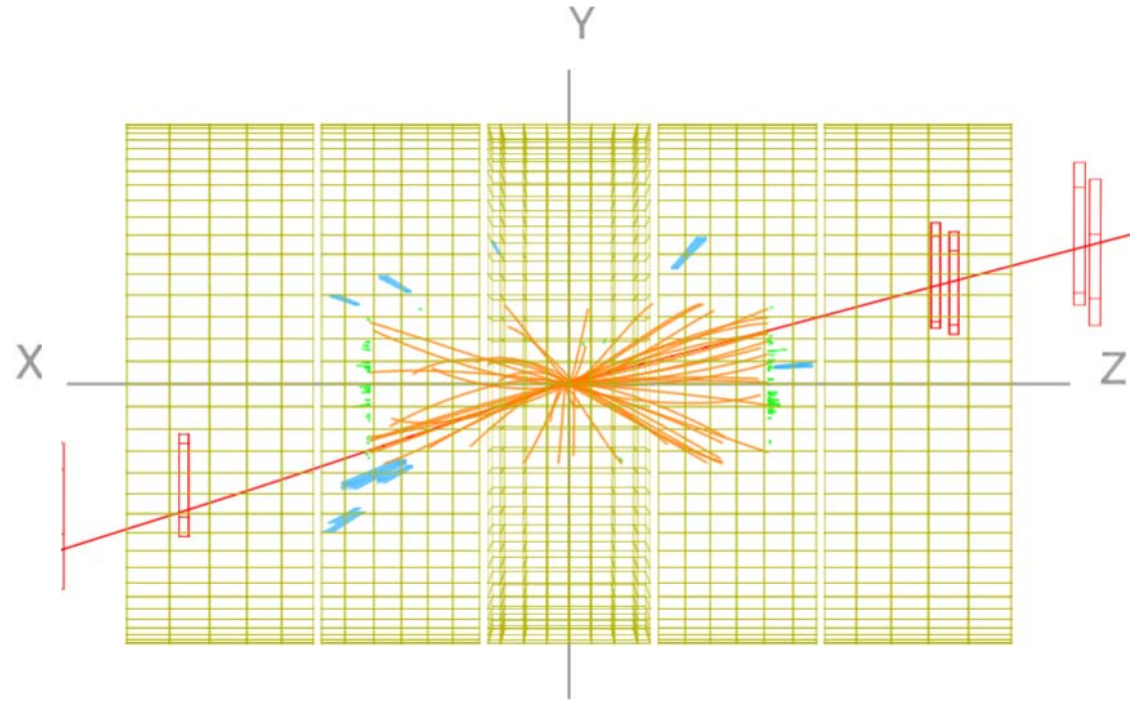


z-y view: measure  $\theta$

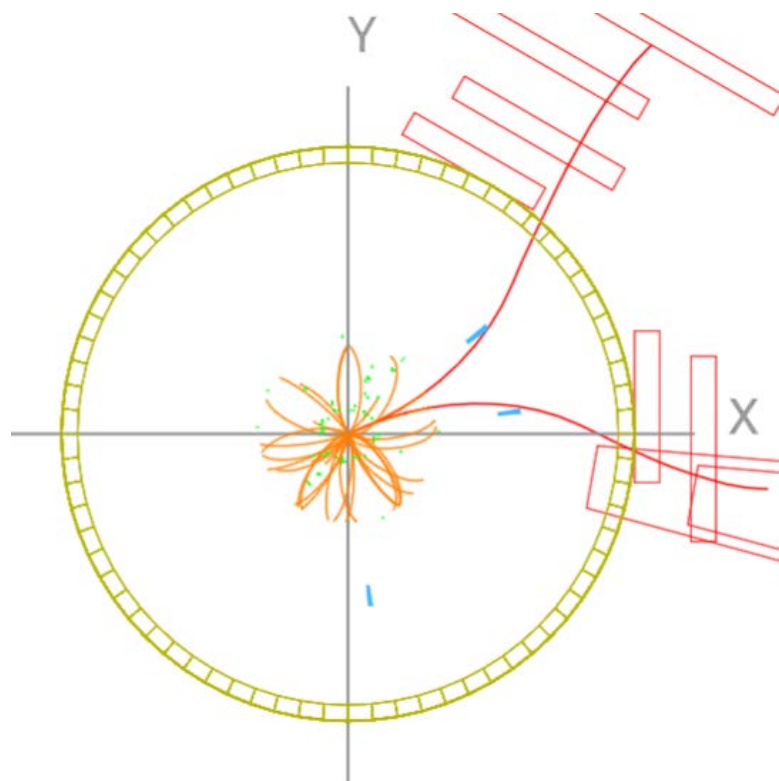




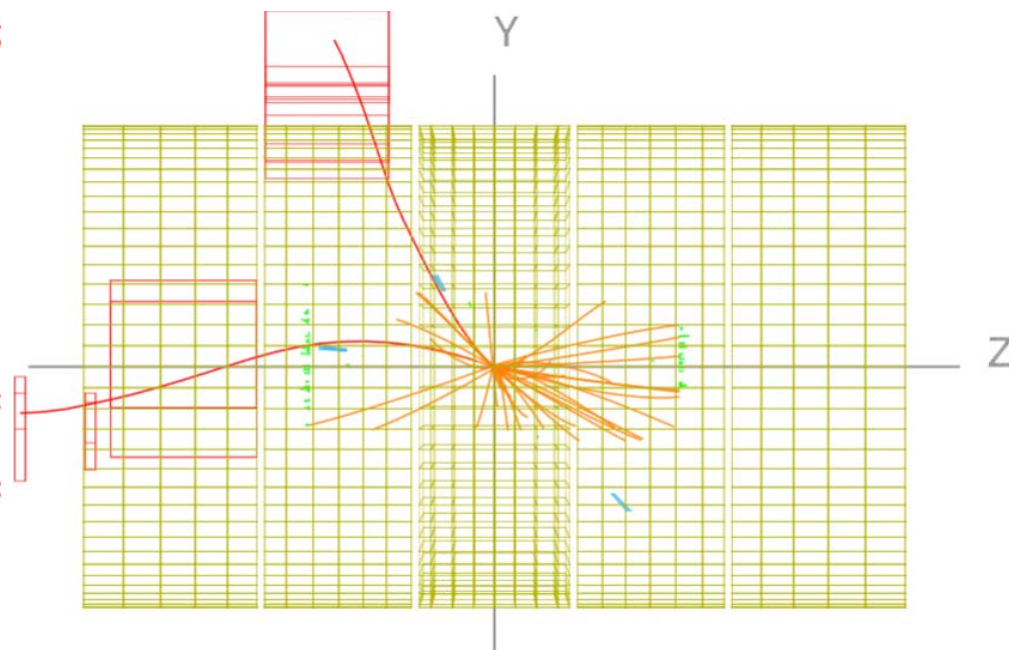
x-y view: measure  $\phi$



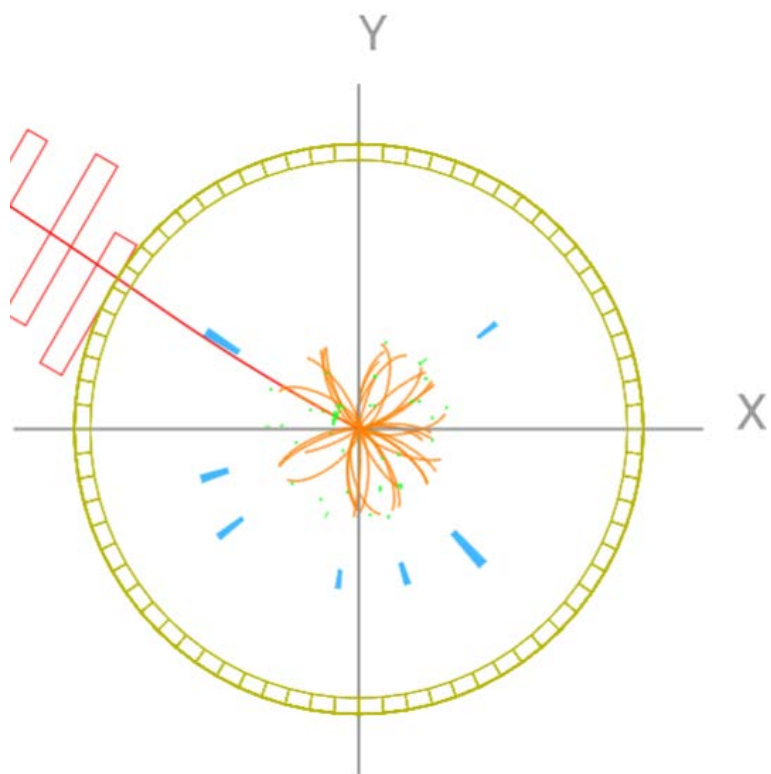
z-y view: measure  $\theta$



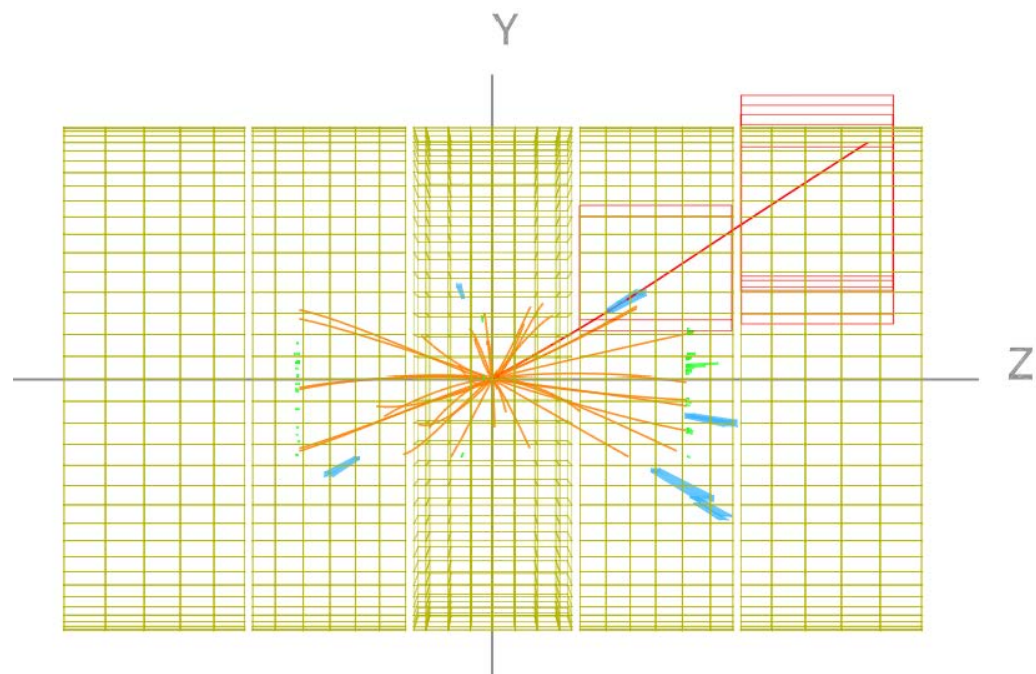
x-y view: measure  $\phi$



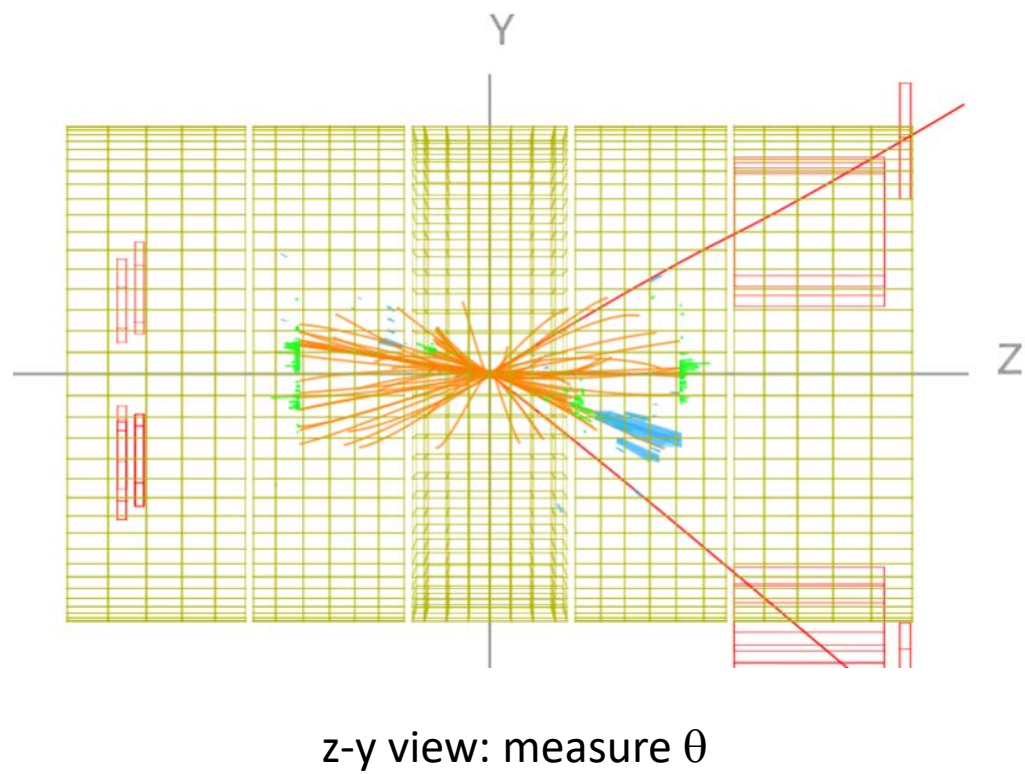
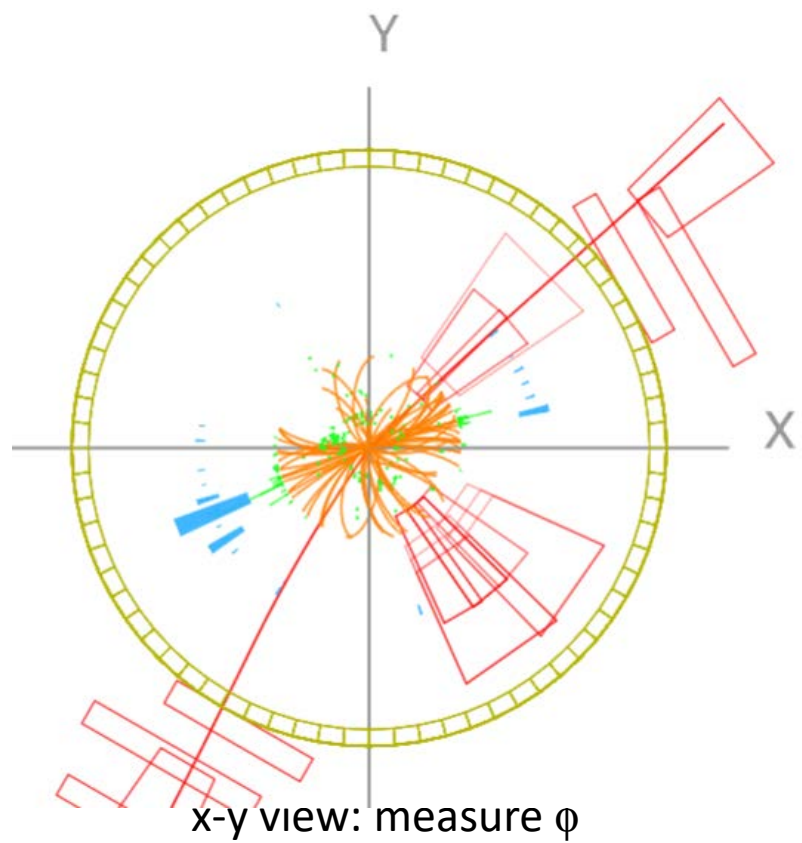
z-y view: measure  $\theta$



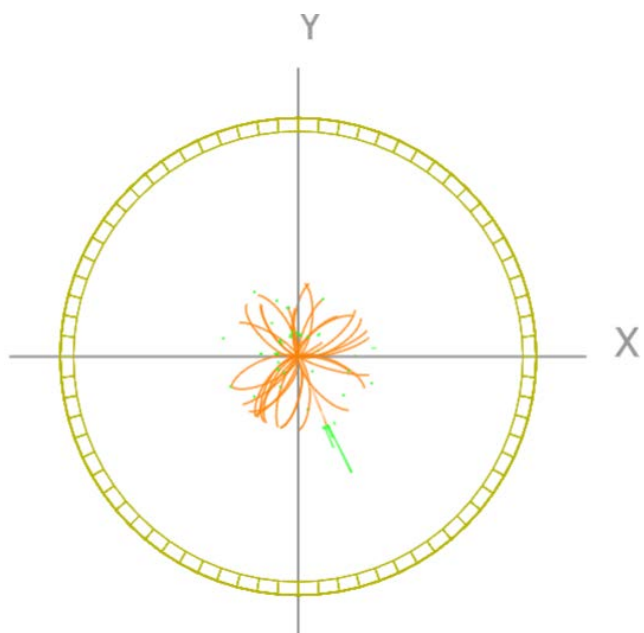
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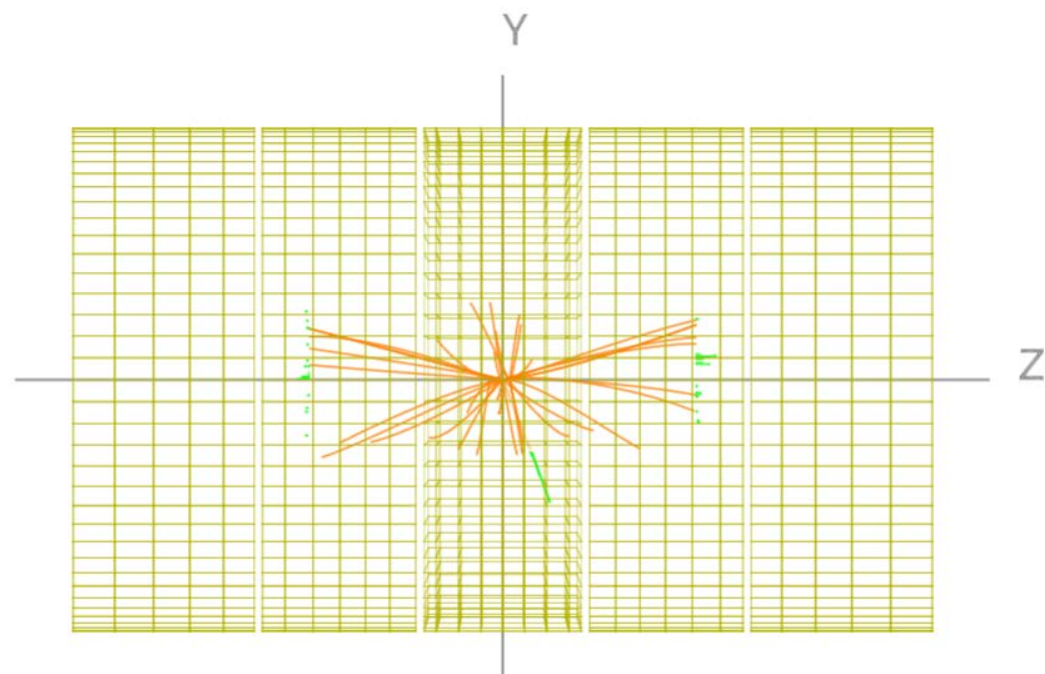
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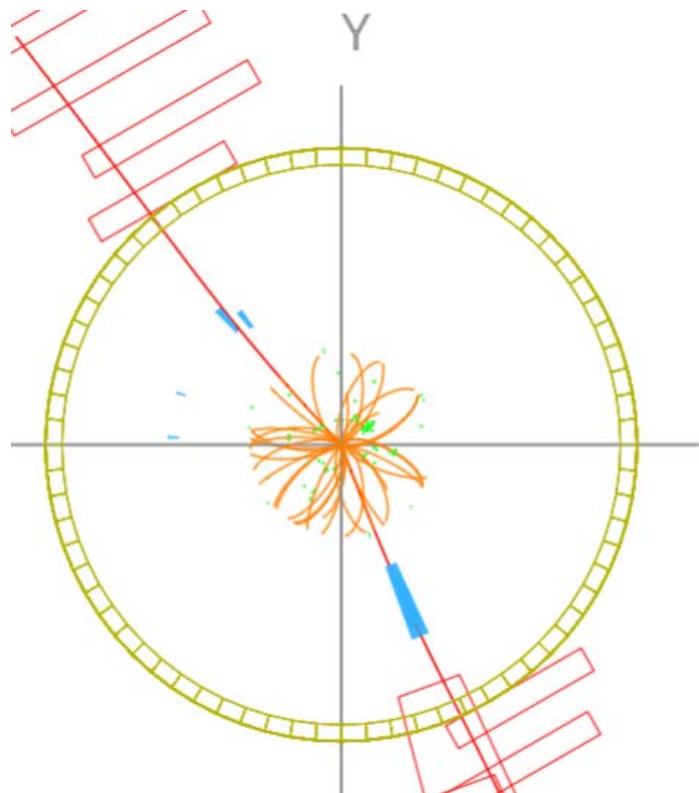


x-y view: measure  $\phi$

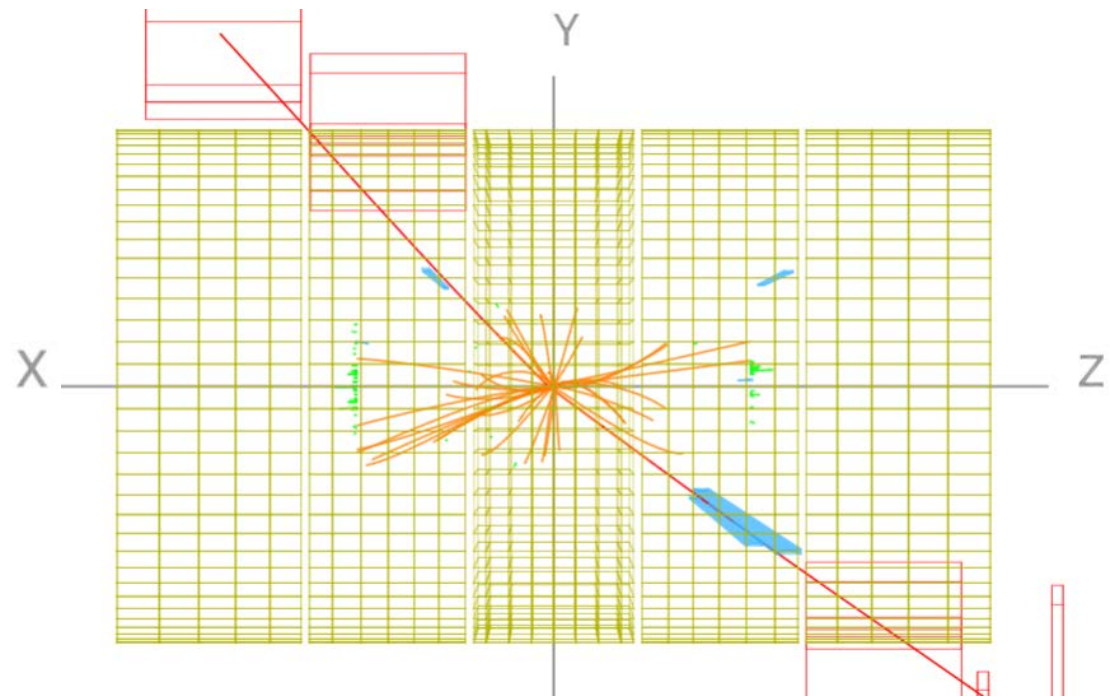


z-y view: measure  $\theta$

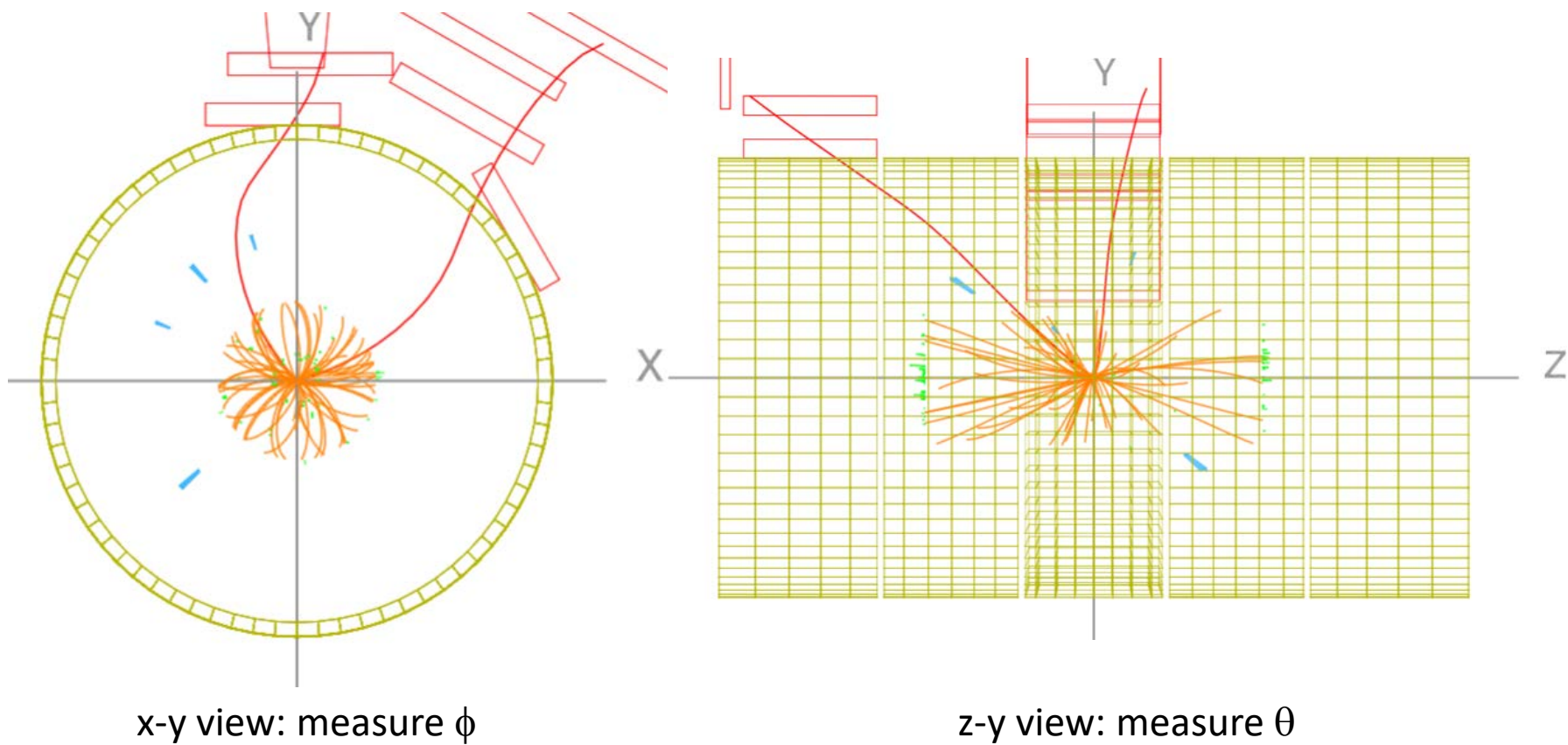


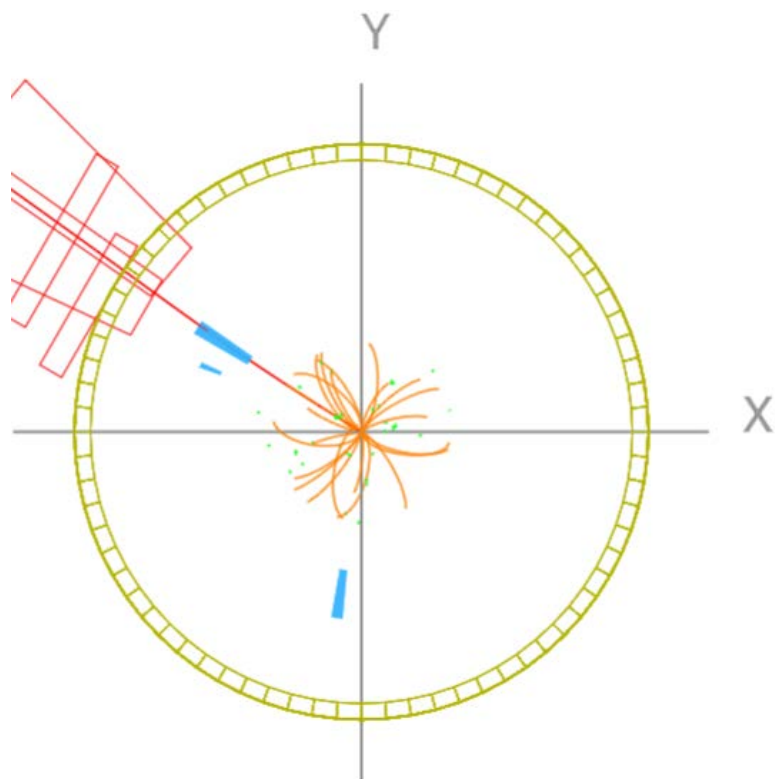


x-y view: measure  $\phi$

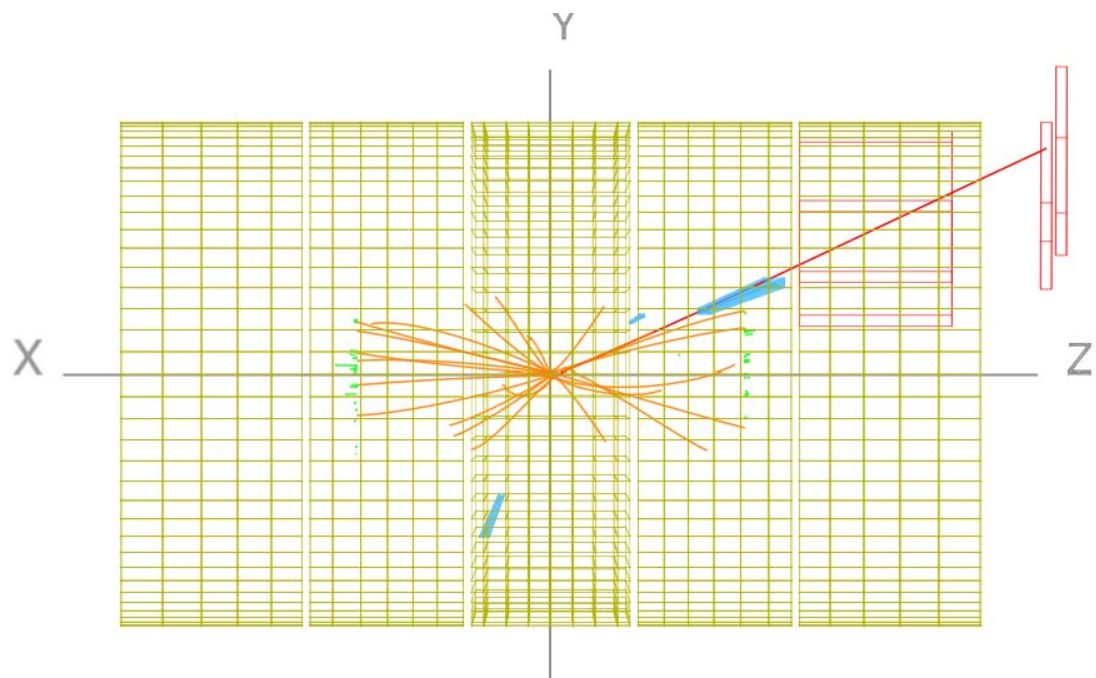


z-y view: measure  $\theta$

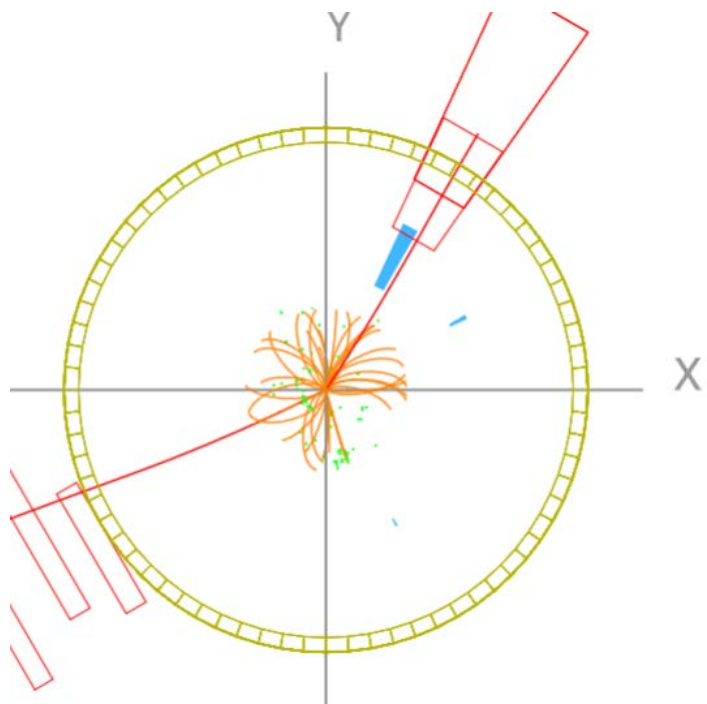




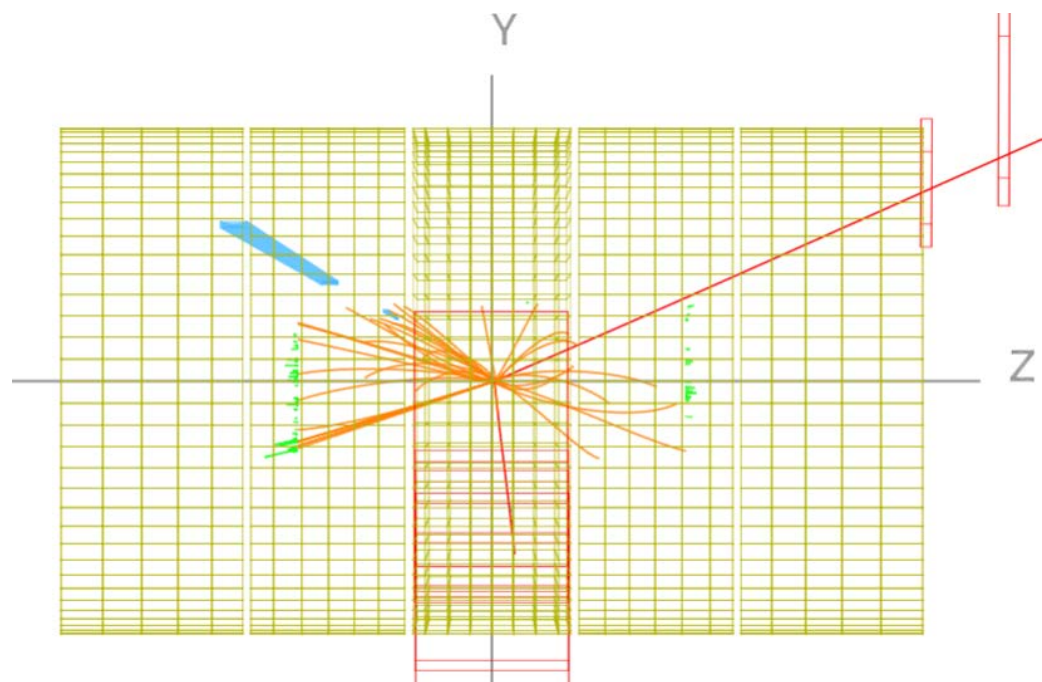
x-y view: measure  $\phi$



z-y view: measure  $\theta$

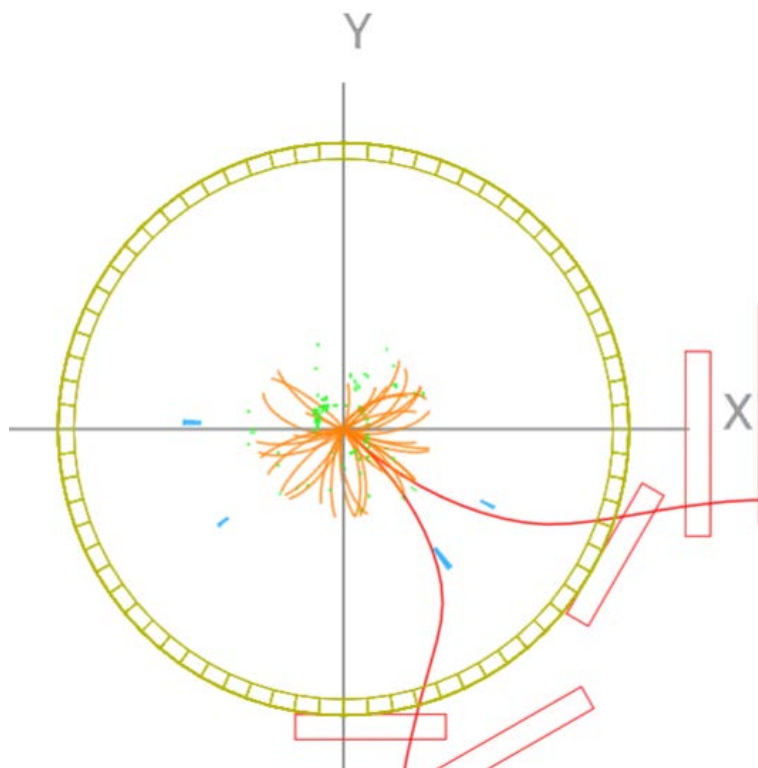


x-y view: measure  $\phi$

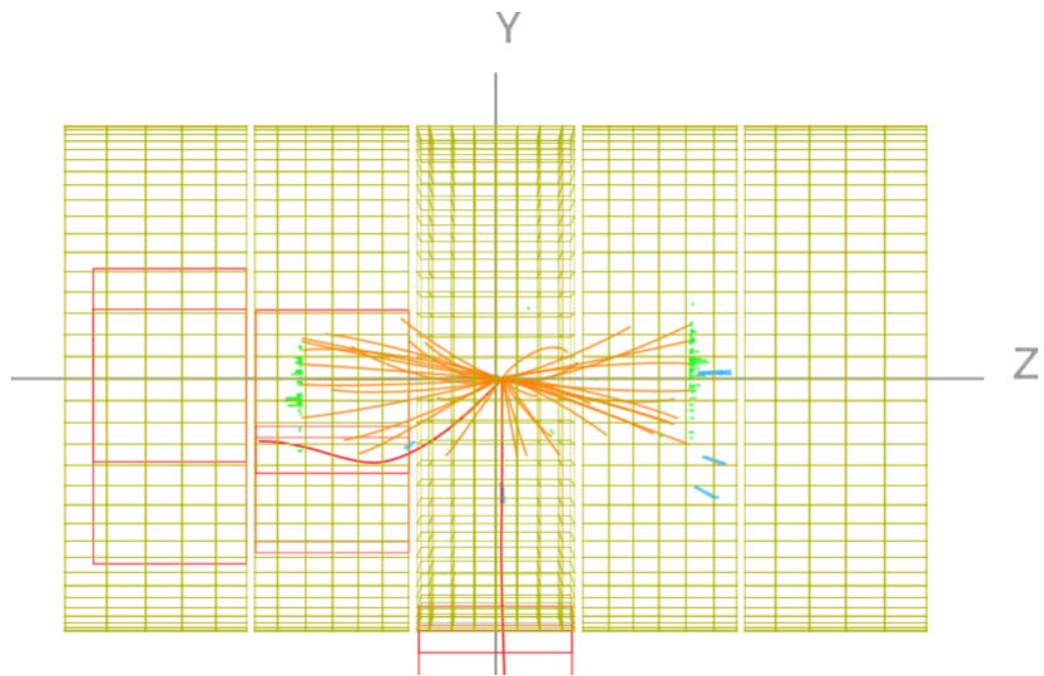


z-y view: measure  $\theta$



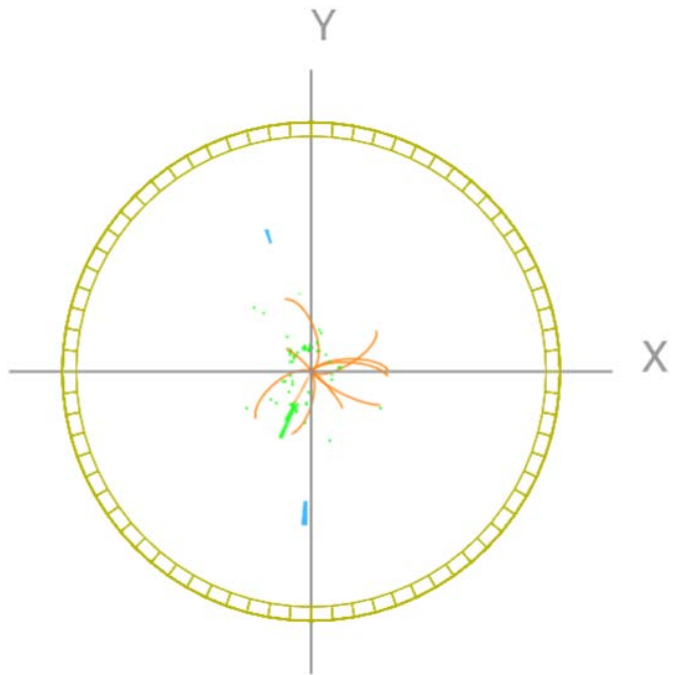


x-y view: measure  $\phi$

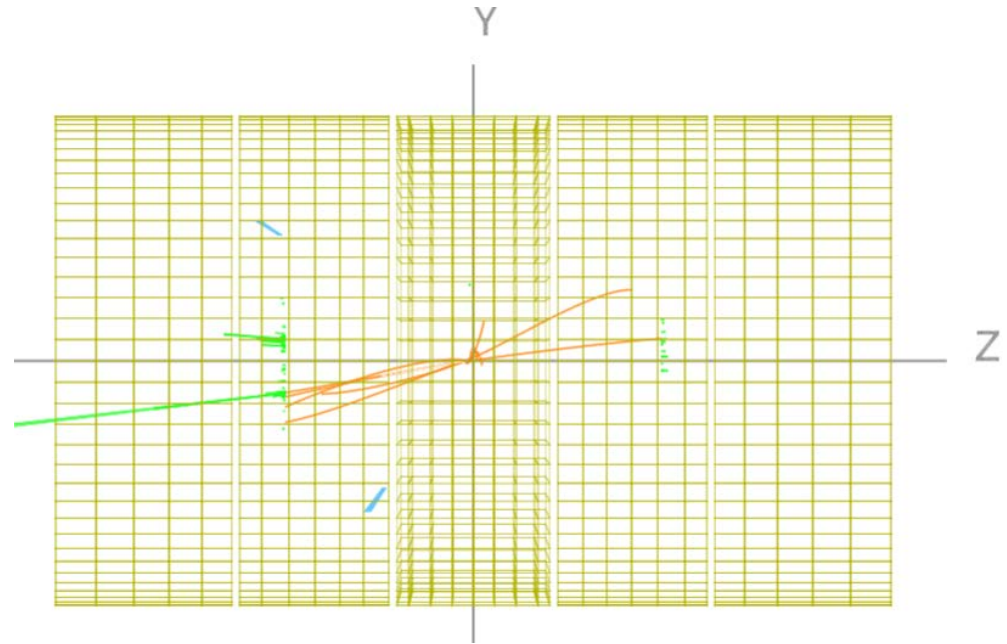


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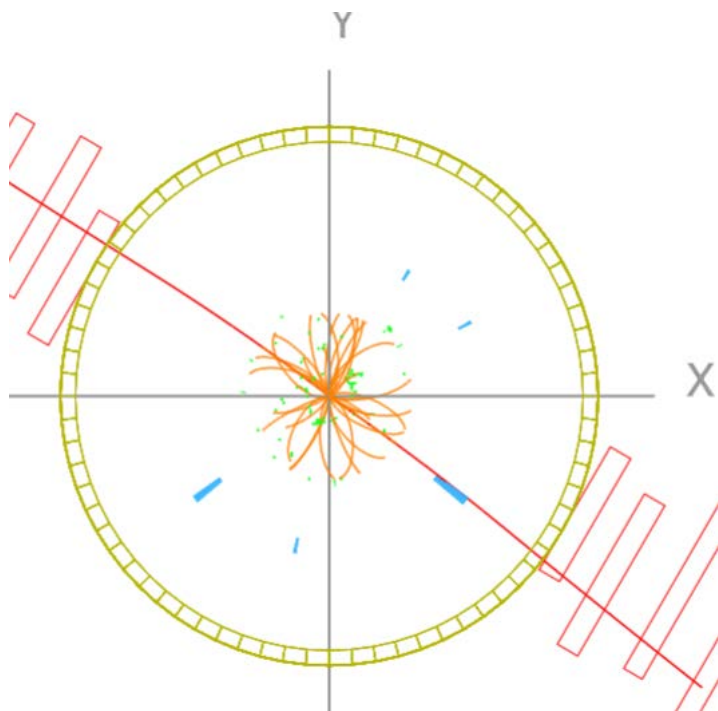




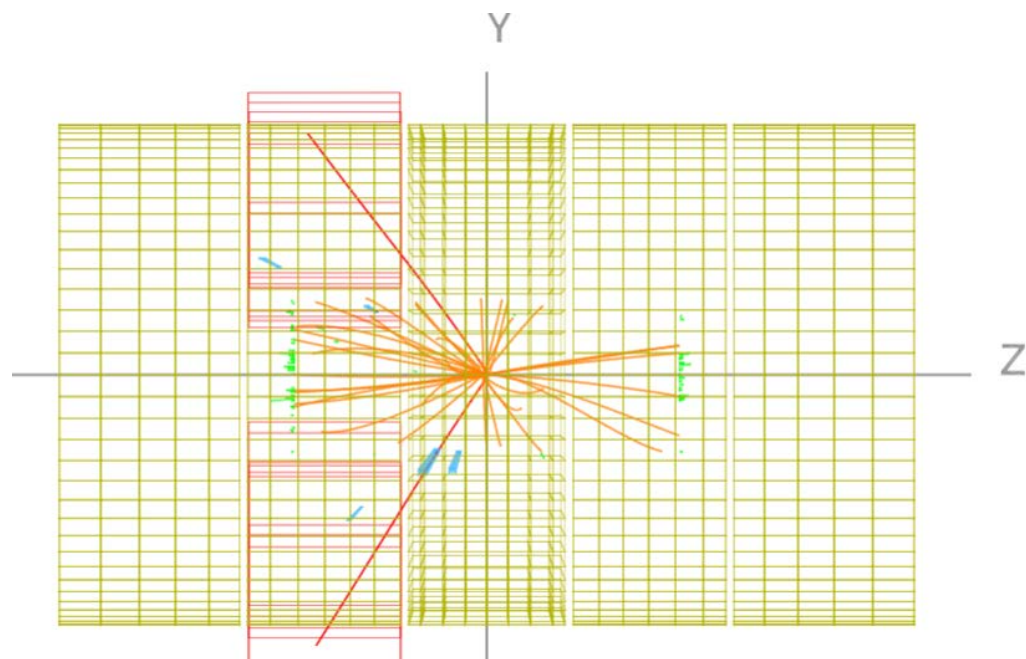
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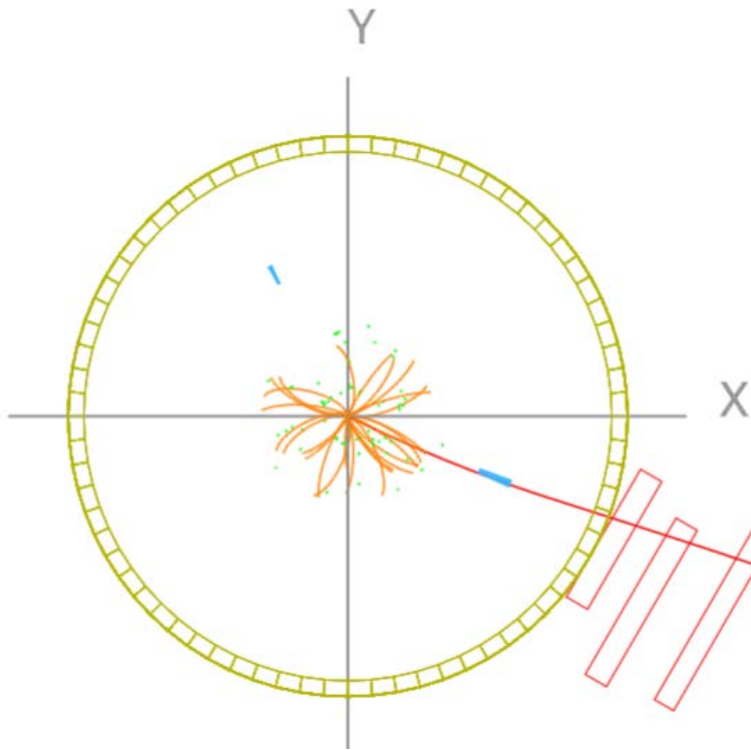
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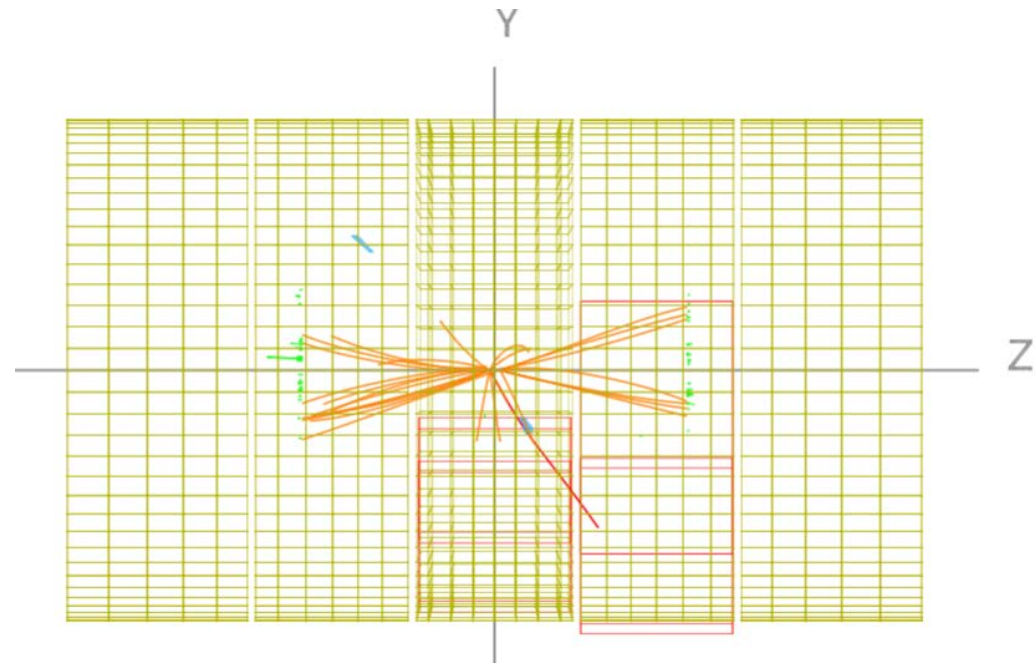
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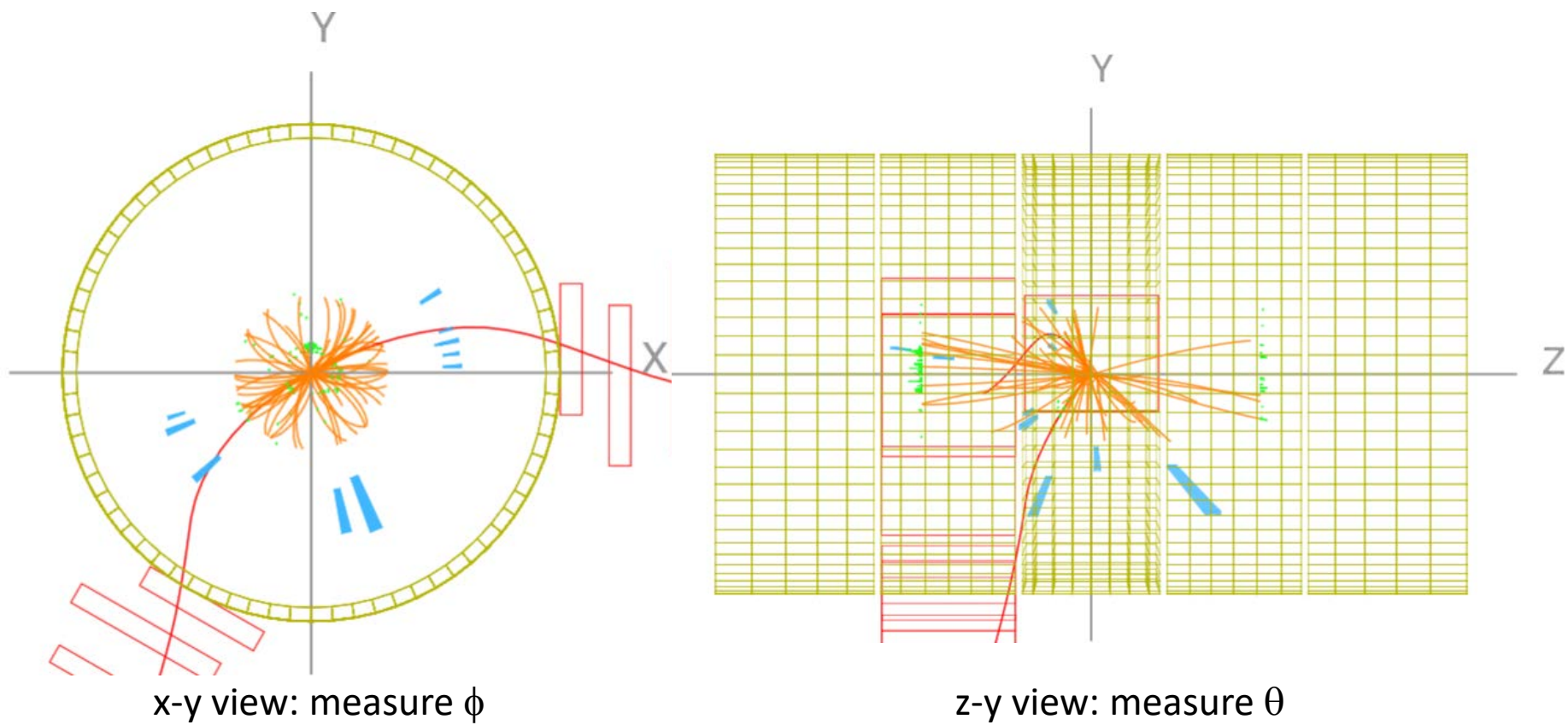
z-y view: measure  $\theta$

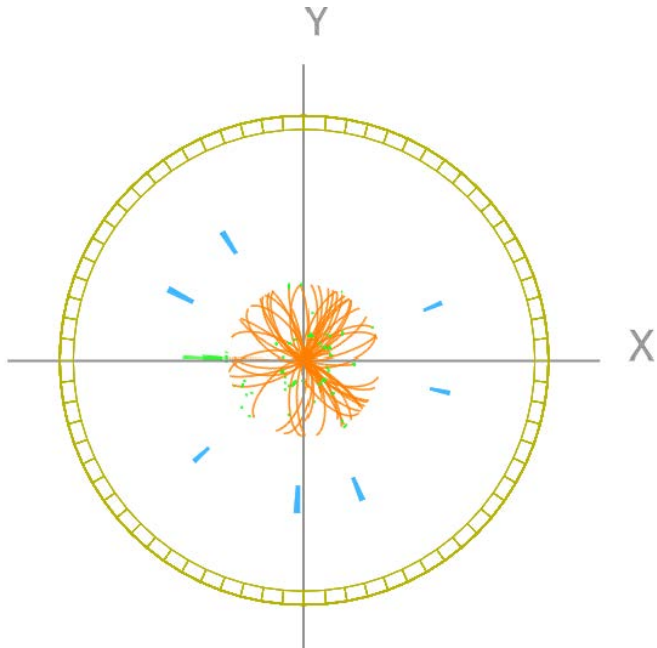


x-y view: measure  $\phi$

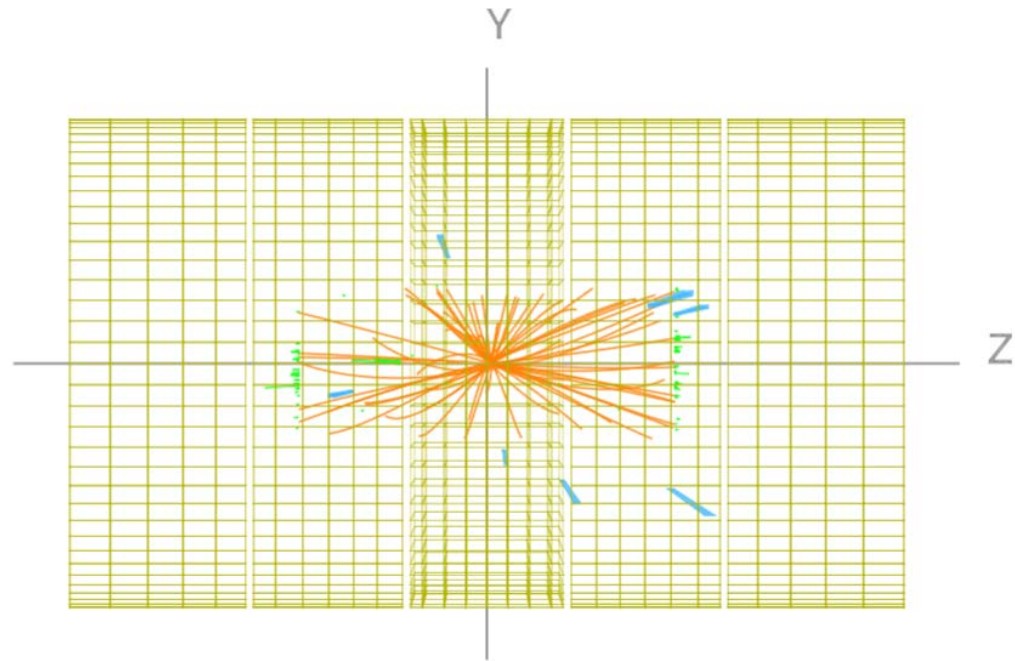


z-y view: measure  $\theta$



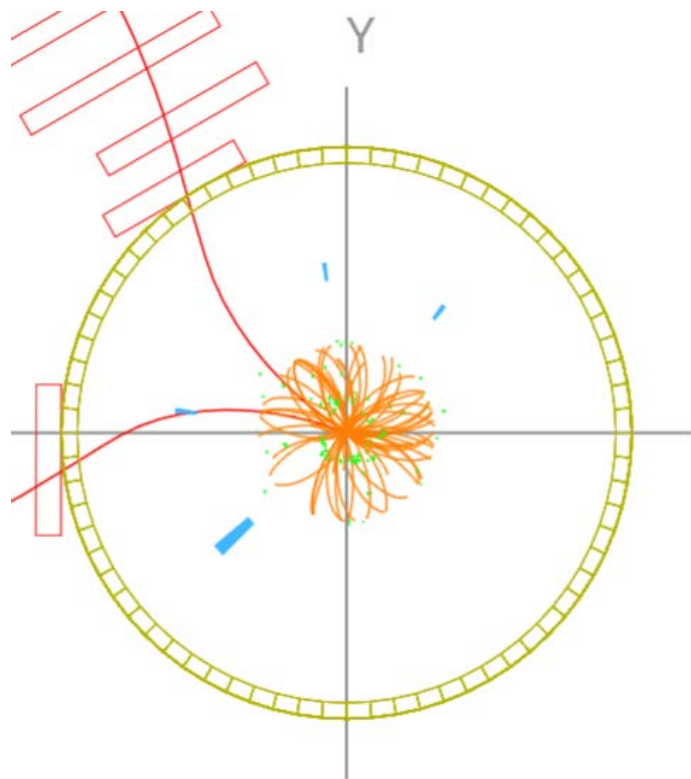


x-y view: measure  $\phi$

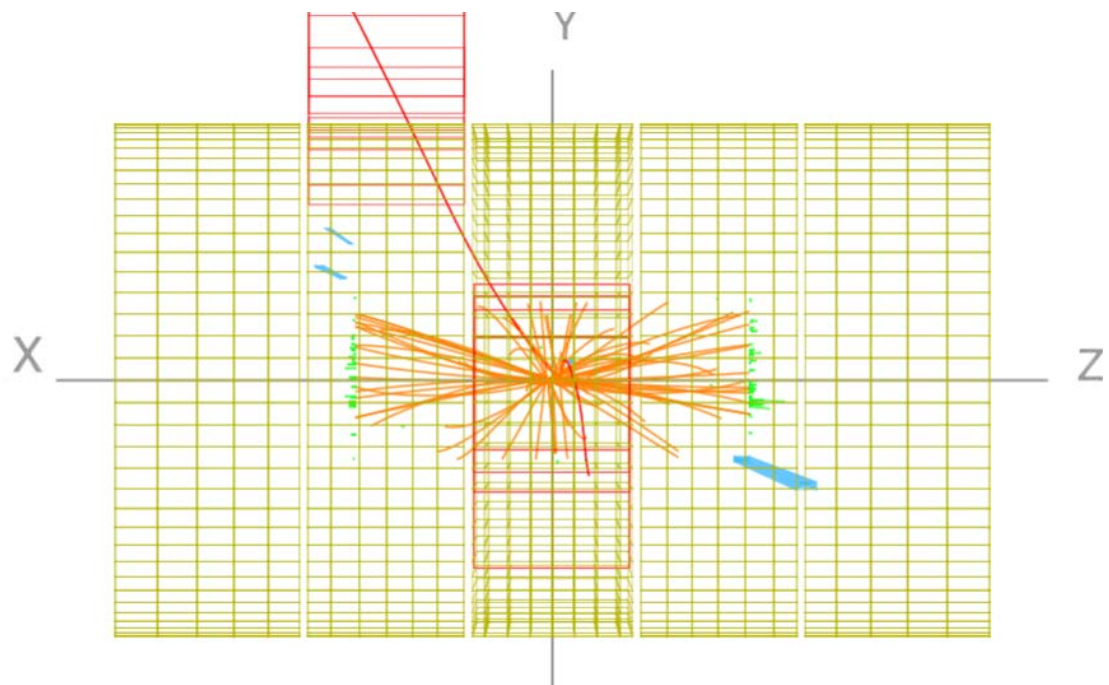


z-y view: measure  $\theta$

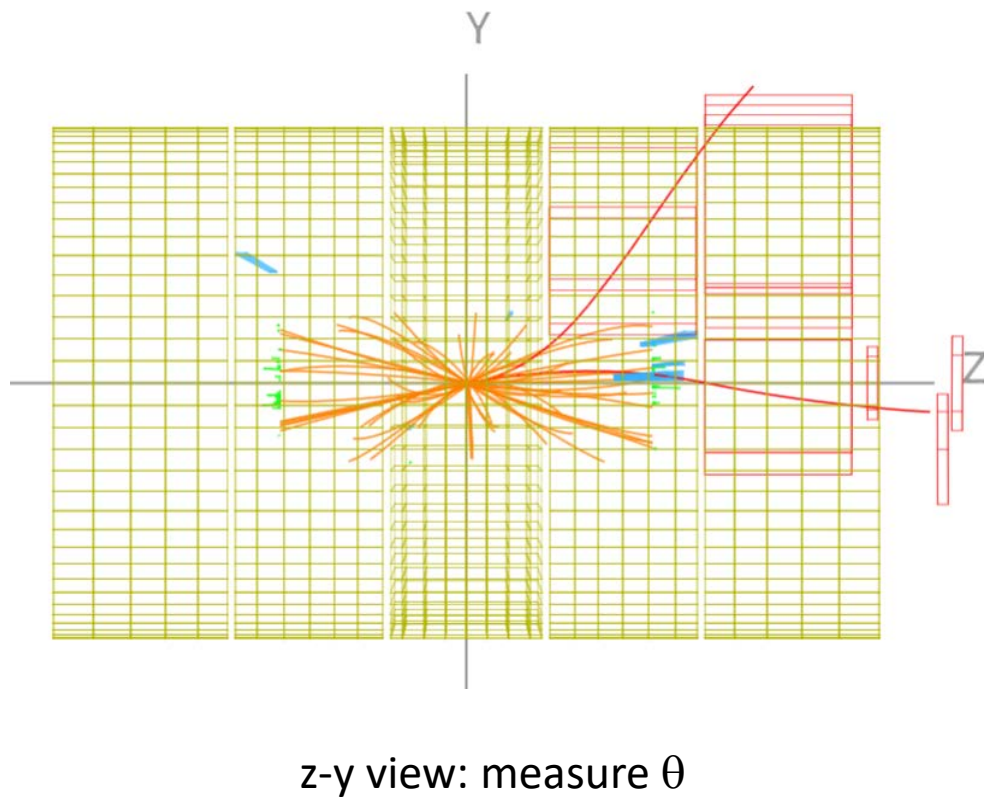
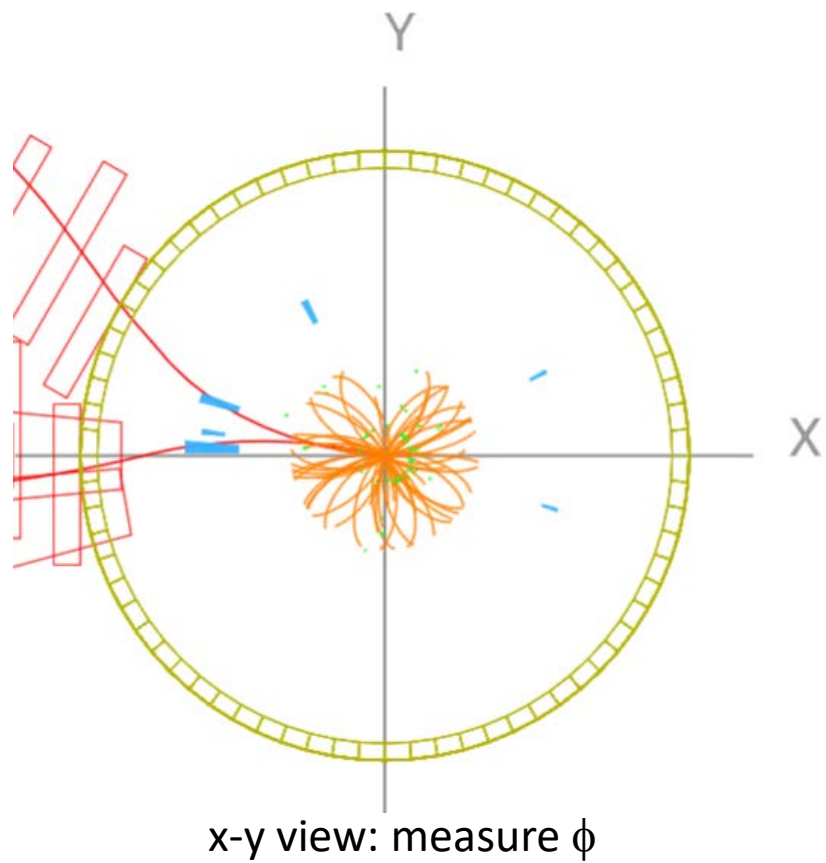


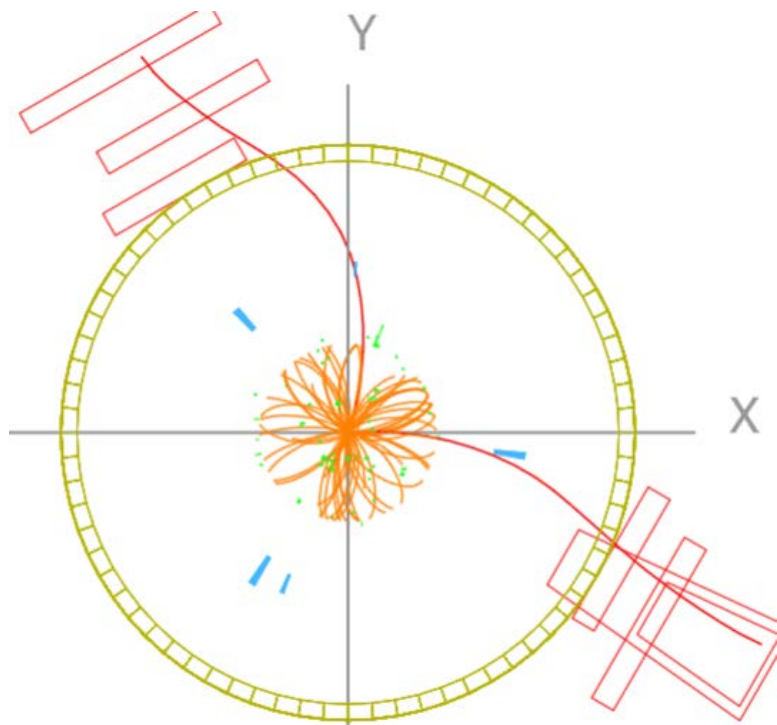


x-y view: measure  $\phi$

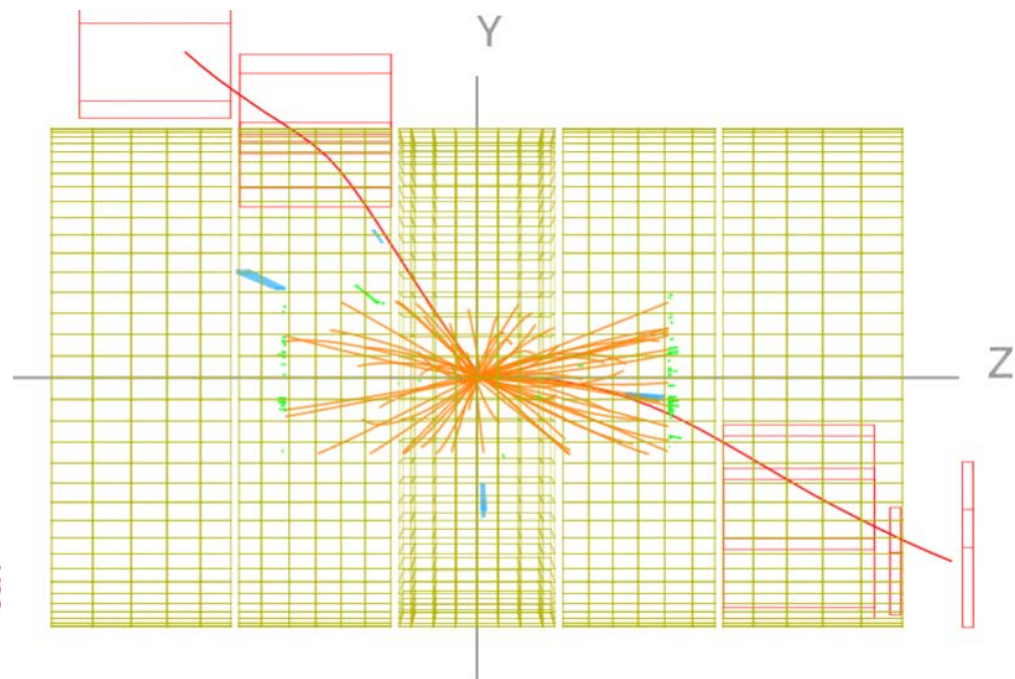


z-y view: measure  $\theta$

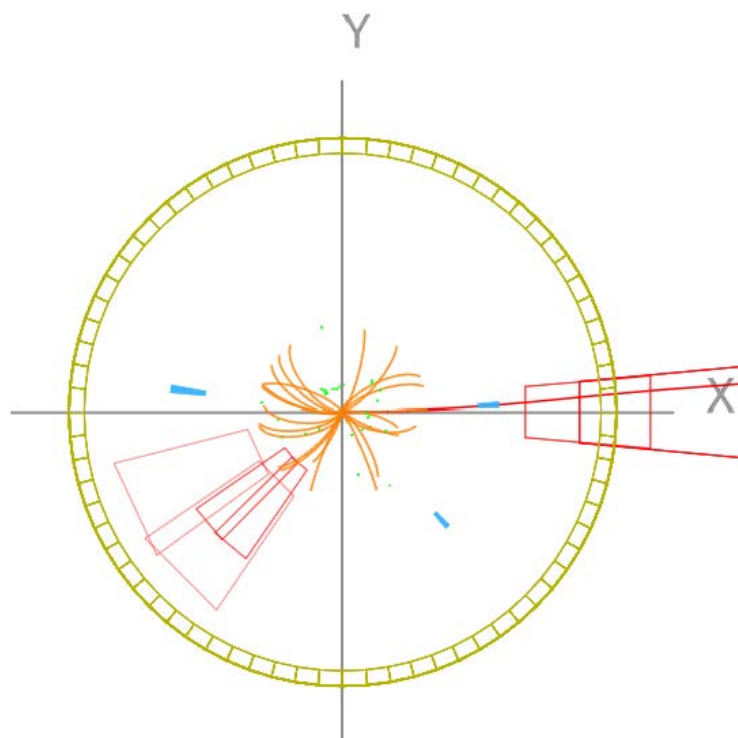




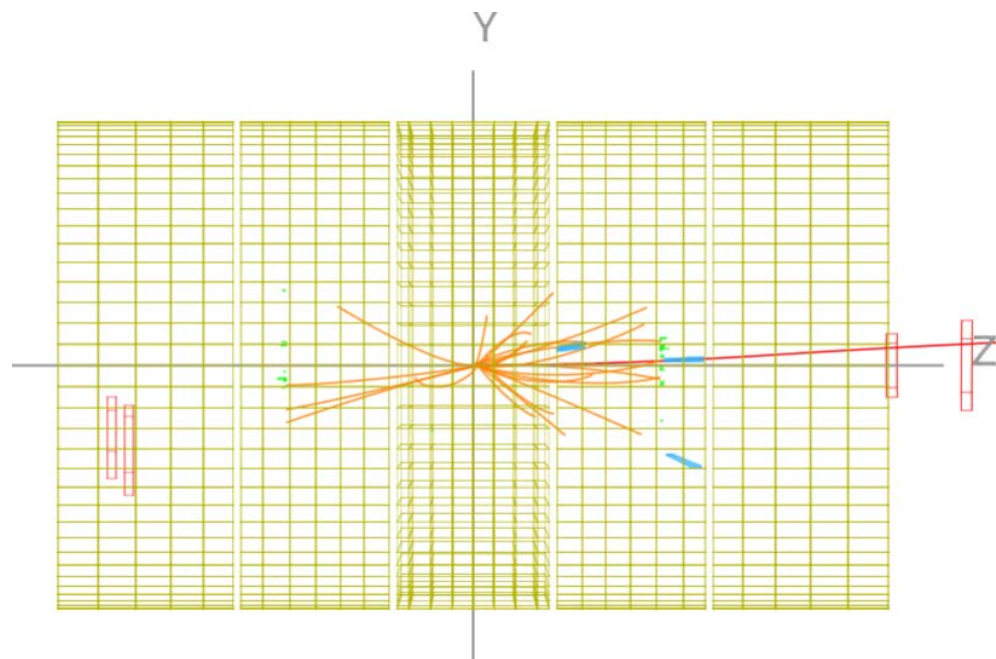
x-y view: measure  $\phi$



z-y view: measure  $\theta$



x-y view: measure  $\phi$



z-y view: measure  $\theta$